



Object  
recognition  
and  
localisation

Melanie Dietz

Outline

Neural  
Networks

Basics  
Feed forward vs.  
backward

Vision and  
localisation

The human  
vision  
Hierarchical  
Networks  
HMAX

Diploma thesis

The hierarchical  
network  
Adding feedback  
connections  
Training and  
analysis

# Object recognition and localisation

## Diplomarbeit

Melanie Dietz

TU München

November 24, 2005



## 1 Neural Networks

- Basics
- Feed forward vs. backward

## 2 Vision and localisation

- The human vision
- Hierarchical Networks
- HMAX

## 3 Diploma thesis

- The hierarchical network
- Adding feedback connections
- Training and analysis



# Basics

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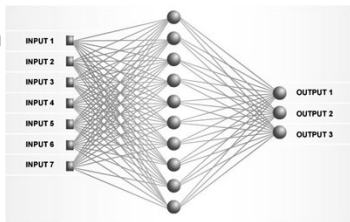
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The hierarchical  
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Training and  
analysis

- Modelled on biological system
- It works! (look in a mirror)
- Components:
  - 1 nodes
  - 2 weighted connections
- many types (unidirectional, bidirectional, layered, hierarchical, ...)
- empirical design or training of weights





# Feed forward vs. backward

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- *Feed forward*  
'A feed-forward network can be viewed as a graphical representation of parametric function which takes a set of input values and maps them to a corresponding set of output values (Bishop, 1995).'  
⇒: classification and prediction applications
- *Feed backward*
  - No declared output nodes
  - Instead output is fed back as input signal⇒: optimization applications



# The visual cortex

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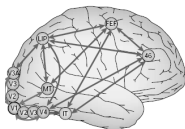
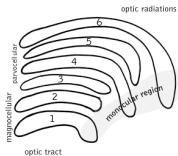
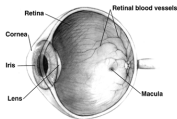
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- The retina
- LGN
- Visual cortical areas
- Visual pathways
- Hierarchical structure



# Hierarchical Networks

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- nodes are arranged in layers
- information gain per layer increases
- number of nodes per layer decreases
- new concepts:
  - *physical position in lower layers*
  - *receptive fields*
  - *translation invariance (2D)*



# Simple and complex cells

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## Hubel and Wiesel (1962)

- Simple cells
  - small receptive fields
  - strong phase dependence
- Complex cells
  - larger receptive fields
  - no phase dependence



# HMAX

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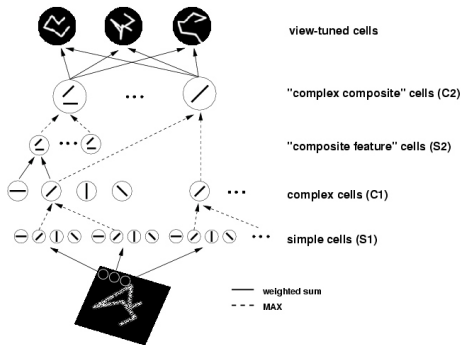
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## Riesenhuber and Poggio (1982)

- pooling operation  
→ *view invariance*  
(3D)
- simple and complex  
cells







# The hierarchical network

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- implementation modelled on HMAX
- First layer: noise reduction
- Second layer: S1 (orientation filter)  
C1 (orientation collection)
- Third layer: S2 (simple features)  
C2 (complex features)
- Forth layer: view-tuned cells



# Orientation detection

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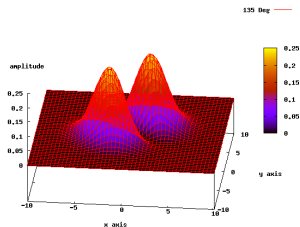
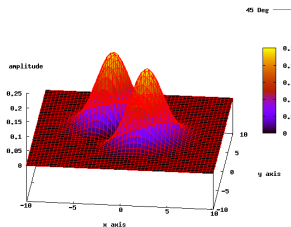
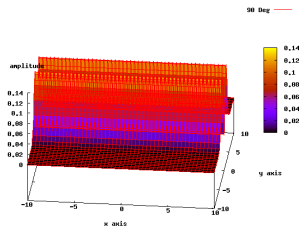
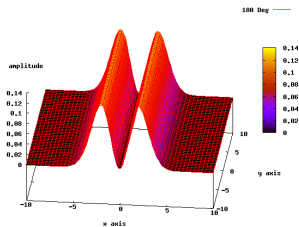
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Training and  
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- usage of BP for VTU's
- creation of training data
- composition of training sets
- comparison to HMAX (Matlab version)



# Adding feedback connections

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- not only ventral stream but also dorsal stream
- backward connections for asking where the object was
- usage of shape AND color for object recognition