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(3) If **RR**-iteration terminates after d rounds, then
 $(x_1^{(d)}, \dots, x_n^{(d)})$ is a solution $:-))$

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The efficiency of **RR**-iteration depends on the **ordering** of the unknowns

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- u before v , if $u \rightarrow^* v$;
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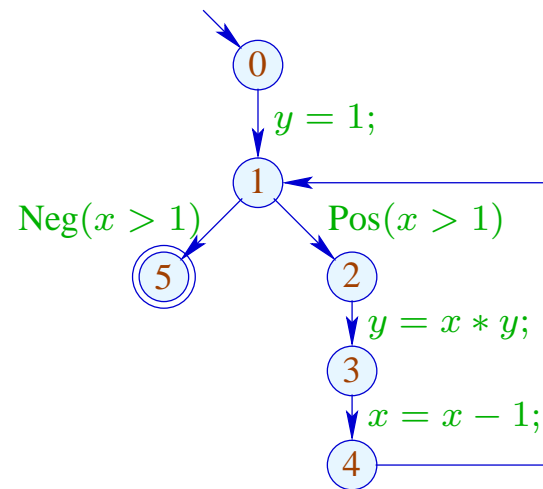
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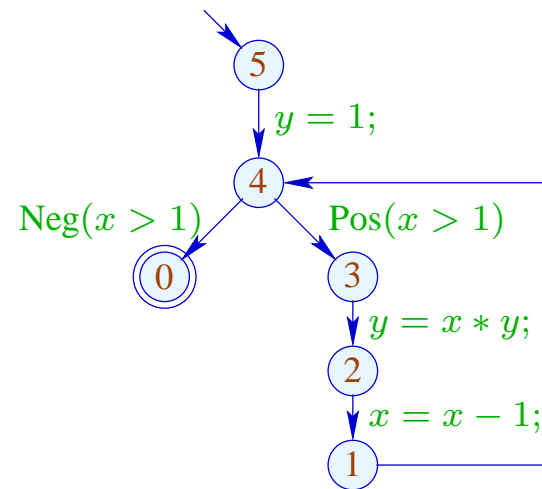
Bad:

e.g., post-order DFS of the CFG, starting at **start** :-)

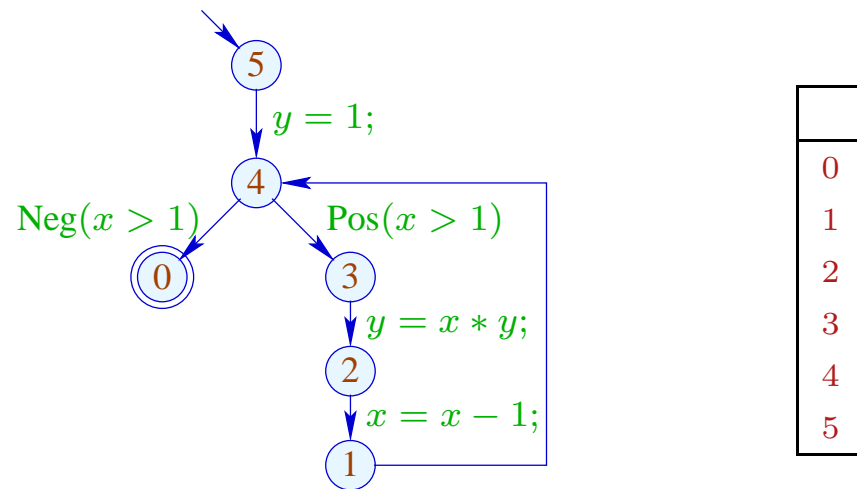
Good:



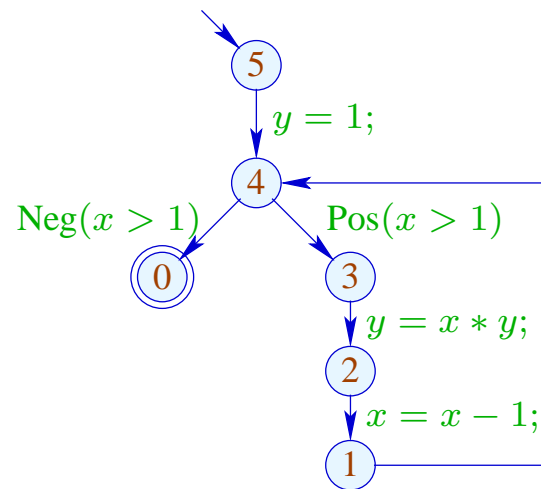
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Inefficient Round Robin Iteration:

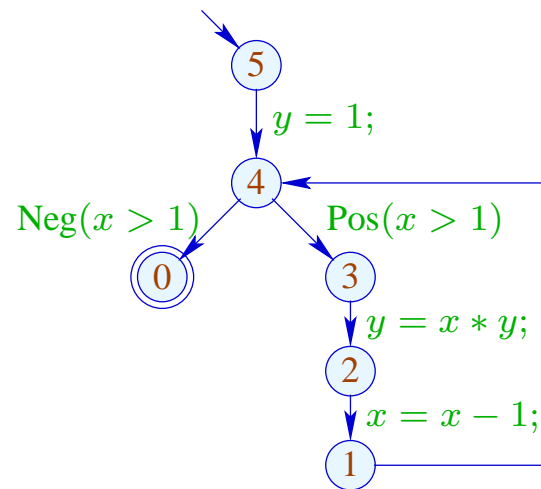


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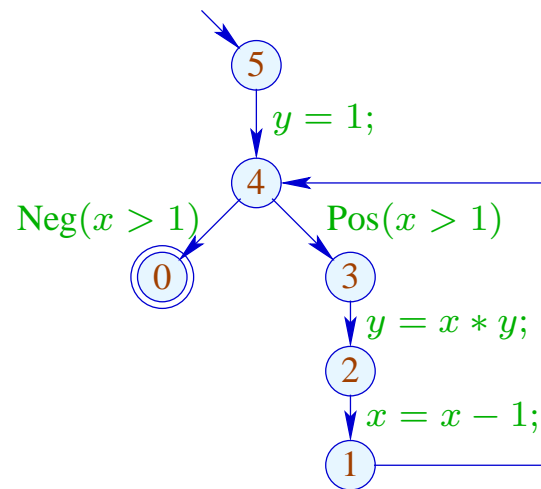
	1
0	<i>Expr</i>
1	$\{1\}$
2	$\{1, x - 1, x > 1\}$
3	<i>Expr</i>
4	$\{1\}$
5	\emptyset

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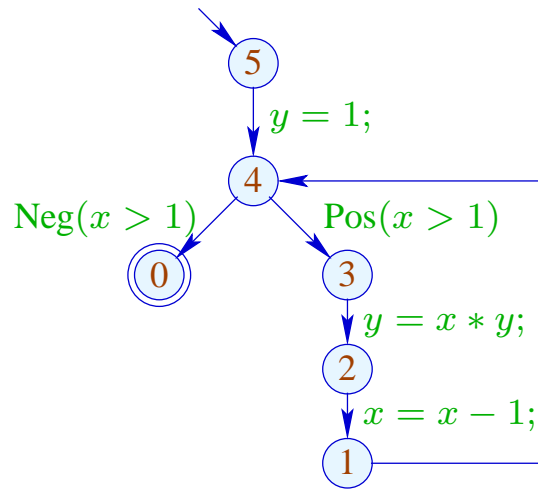
	1	2
0	<i>Expr</i>	$\{1, x > 1\}$
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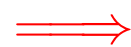


	1	2	3
0	<i>Expr</i>	$\{1, x > 1\}$	$\{1, x > 1\}$
1	$\{1\}$	$\{1\}$	$\{1\}$
2	$\{1, x - 1, x > 1\}$	$\{1, x - 1, x > 1\}$	$\{1, x > 1\}$
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	1	2	3	4
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... end of background on: Complete Lattices

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Final Question:

Why is a (or the least) solution of the constraint system useful ???

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For a complete lattice \mathbb{D} , consider systems:

$$\mathcal{I}[\textit{start}] \sqsupseteq d_0$$

$$\mathcal{I}[v] \sqsupseteq \llbracket k \rrbracket^\# (\mathcal{I}[u]) \quad k = (u, _, v) \text{ edge}$$

where $d_0 \in \mathbb{D}$ and all $\llbracket k \rrbracket^\# : \mathbb{D} \rightarrow \mathbb{D}$ are monotonic ...

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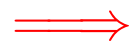
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Monotonic Analysis Framework

Wanted: MOP (Merge Over all Paths)

$$\mathcal{I}^*[v] = \bigsqcup \{ \llbracket \pi \rrbracket^\# d_0 \mid \pi : \textit{start} \rightarrow^* v \}$$

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Theorem

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Jeffrey D. Ullman, Stanford

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$$\mathcal{I}[v] \supseteq \mathcal{I}^*[v] \quad \text{for every } v$$

In particular: $\mathcal{I}[v] \supseteq \llbracket \pi \rrbracket^\# d_0$ for every $\pi : \textit{start} \rightarrow^* v$

Proof: Induction on the length of π .

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Then:

$$\llbracket \pi' \rrbracket^\# d_0 \sqsubseteq \mathcal{I}[u] \quad \text{by I.H. for } \pi$$

$$\begin{aligned} \implies \llbracket \pi \rrbracket^\# d_0 &= \llbracket k \rrbracket^\# (\llbracket \pi' \rrbracket^\# d_0) \\ &\sqsubseteq \llbracket k \rrbracket^\# (\mathcal{I}[u]) && \text{since } \llbracket k \rrbracket^\# \text{ monotonic} \\ &\sqsubseteq \mathcal{I}[v] && \text{since } \mathcal{I} \text{ solution } :-)) \end{aligned}$$

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With the notable exception when all functions $\llbracket k \rrbracket^\#$ are **distributive** ...
:-)

The function $f : \mathbb{D}_1 \rightarrow \mathbb{D}_2$ is called

- **distributive**, if $f(\bigsqcup X) = \bigsqcup \{f x \mid x \in X\}$ for all $\emptyset \neq X \subseteq \mathbb{D}$;
- **strict**, if $f \perp = \perp$.
- **totally distributive**, if f is distributive and strict.

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Distributivity:

$$\begin{aligned}
 f(x_1 \cup x_2) &= a \cap (x_1 \cup x_2) \cup b \\
 &= a \cap x_1 \cup a \cap x_2 \cup b \\
 &= f x_1 \cup f x_2 \quad \quad \quad :-)
 \end{aligned}$$

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Distributivity:

$$\begin{aligned} f((1, 4) \sqcup (4, 1)) &= f(4, 4) = 8 \\ &\neq 5 = f(1, 4) \sqcup f(4, 1) \quad :-) \end{aligned}$$

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From that follows:

$$\begin{aligned} f b &= f (a \sqcup b) \\ &= f a \sqcup f b \\ \implies f a &\sqsubseteq f b \quad \text{:-)} \end{aligned}$$

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Then:

Theorem

Kildall 1972

If **all** effects of edges $\llbracket k \rrbracket^\#$ are distributive, then: $\mathcal{I}^*[v] = \mathcal{I}[v]$
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Gary A. Kildall (1942-1994).

Has developed the operating system CP/M and GUIs for PCs.

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Proof:

It suffices to prove that \mathcal{I}^* is a solution $:-)$

For this, we show that \mathcal{I}^* satisfies all constraints $:-))$

(1) We prove for *start* :

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&\sqsupseteq d_0 \quad :-)
\end{aligned}$$

(2) For every $k = (u, _, v)$ we prove:

$$\begin{aligned}
\mathcal{I}^*[v] &= \bigsqcup \{ \llbracket \pi \rrbracket^\# d_0 \mid \pi : start \rightarrow^* v \} \\
&\sqsupseteq \bigsqcup \{ \llbracket \pi' k \rrbracket^\# d_0 \mid \pi' : start \rightarrow^* u \} \\
&= \bigsqcup \{ \llbracket k \rrbracket^\# (\llbracket \pi' \rrbracket^\# d_0) \mid \pi' : start \rightarrow^* u \} \\
&= \llbracket k \rrbracket^\# (\bigsqcup \{ \llbracket \pi' \rrbracket^\# d_0 \mid \pi' : start \rightarrow^* u \}) \\
&= \llbracket k \rrbracket^\# (\mathcal{I}^*[u])
\end{aligned}$$

since $\{ \pi' \mid \pi' : start \rightarrow^* u \}$ is non-empty $:-)$

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- **Reachability** of all program points cannot be abandoned! Consider:



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$$\mathcal{I}[2] = \text{inc } 0 = 1$$

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- **Unreachable** program points can always be thrown away :-)

Summary and Application:

- The effects of edges of the analysis of **availability of expressions** are distributive:

$$\begin{aligned}(a \cup (x_1 \cap x_2)) \setminus b &= ((a \cup x_1) \cap (a \cup x_2)) \setminus b \\ &= ((a \cup x_1) \setminus b) \cap ((a \cup x_2) \setminus b)\end{aligned}$$

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- If all effects of edges are **distributive**, then the **MOP** can be computed by means of the constraint system and **RR-iteration**. :-)
- If **not all** effects of edges are **distributive**, then **RR-iteration** for the constraint system at least returns a **safe** upper bound to the MOP :-)

1.2 Removing Assignments to Dead Variables

Example:

1 : $x = y + 2;$

2 : $y = 5;$

3 : $x = y + 3;$

The value of x at program points 1, 2 is over-written before it can be used.

Therefore, we call the variable x **dead** at these program points :-)

Note:

- Assignments to dead variables can be removed ;-)
- Such inefficiencies may originate from other transformations.

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Formal Definition:

The variable x is called **live** at u along the path π starting at u relative to a set X of variables either:

if $x \in X$ and π does not contain a **definition** of x ; or:

if π can be decomposed into: $\pi = \pi_1 k \pi_2$ such that:

- k is a **use** of x ; and
- π_1 does not contain a **definition** of x .