

31 Clauses

Clausal code must

- **allocate** stack space for locals;
- **evaluate** the body;
- **free** the stack frame (whenever possible :-)

Let r denote the clause: $p(X_1, \dots, X_k) \leftarrow g_1, \dots, g_n.$

Let $\{X_1, \dots, X_m\}$ denote the set of locals of r and ρ the address environment:

$$\rho X_i = i$$

Remark: The first k locals are always the **formals** :-)

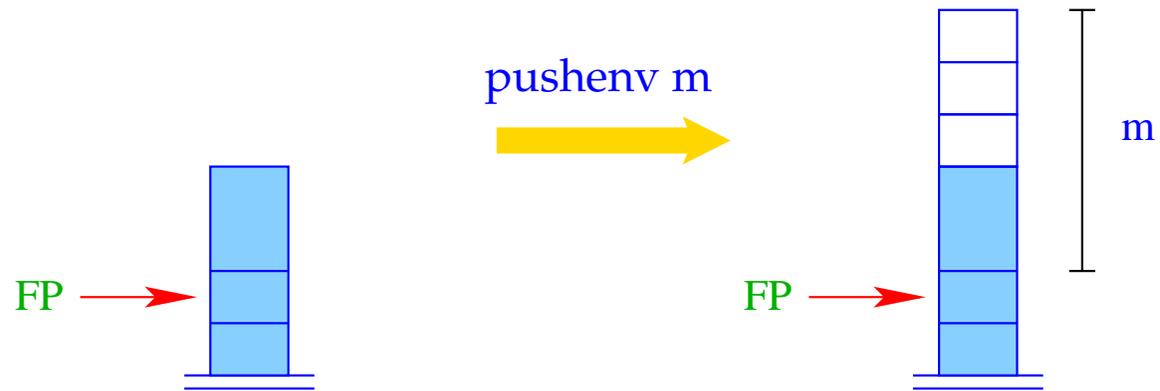
Then we translate:

```
codeC r = pushenv m           // allocates space for locals
          codeG g1 ρ
          ...
          codeG gn ρ
          popenv
```

The instruction `popenv` restores `FP` and `PC` and `tries to pop` the current stack frame.

It should succeed whenever program execution will never return to this stack frame :-)

The instruction `pushenv m` sets the stack pointer:



$$SP = FP + m;$$

Example:

Consider the clause r :

$$a(X, Y) \leftarrow f(\bar{X}, X_1), a(\bar{X}_1, \bar{Y})$$

Then `codeC r` yields:

pushenv 3

mark A

A: mark B

B: popenv

putref 1

putref 3

putvar 3

putref 2

call f/2

call a/2

32 Predicates

A predicate q/k is defined through a sequence of clauses $rr \equiv r_1 \dots r_f$.

The translation of q/k provides the translations of the individual clauses r_i .

In particular, we have for $f = 1$:

$$\text{code}_P rr = \text{code}_C r_1$$

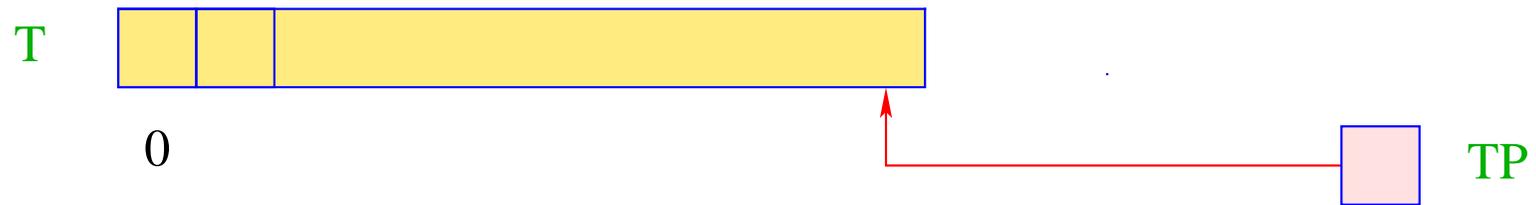
If q/k is defined through several clauses, the first alternative must be tried.

On failure, the next alternative must be tried

\implies backtracking :-)

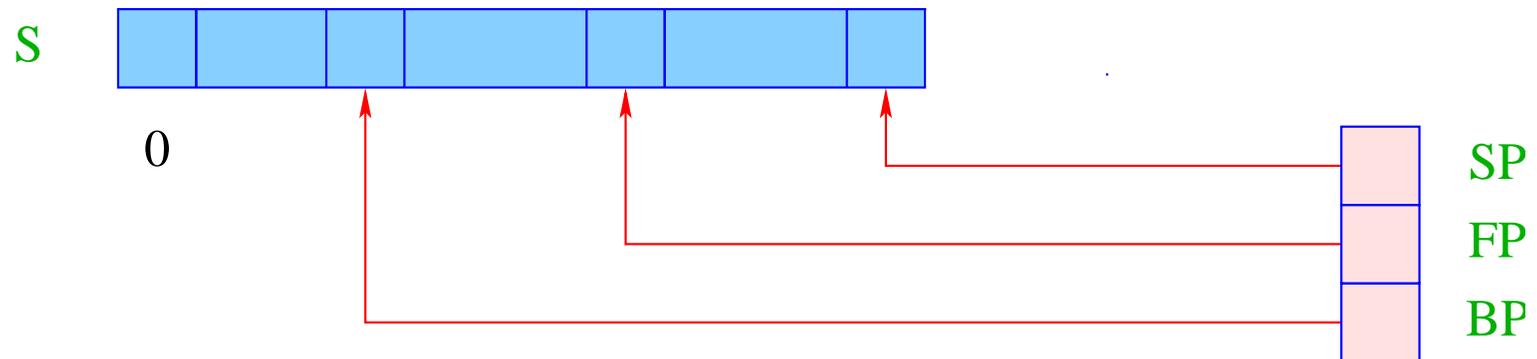
32.1 Backtracking

- Whenever unification fails, we call the run-time function `backtrack()`.
- The goal is to **roll back** the whole computation to the (**dynamically :-**) latest goal where another clause can be chosen \implies the last **backtrack point**.
- In order to undo intermediate variable bindings, we always have recorded new bindings with the run-time function `trail()`.
- The run-time function `trail()` stores variables in the data-structure **trail**:



TP == Trail Pointer
points to the topmost occupied Trail cell

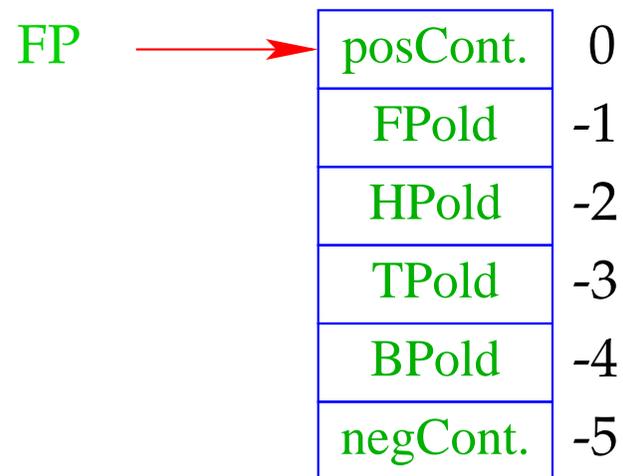
The current stack frame where backtracking should return to is pointed at by the extra register **BP**:



A **backtrack point** is stack frame to which program execution possibly returns.

- We need the code address for trying the **next** alternative (**negative continuation address**);
- We save the old values of the registers **HP**, **TP** and **BP**.
- **Note:** The **new BP** will receive the value of the current **FP** :-)

For this purpose, we use the corresponding four organizational cells:



For more comprehensible notation, we thus introduce the macros:

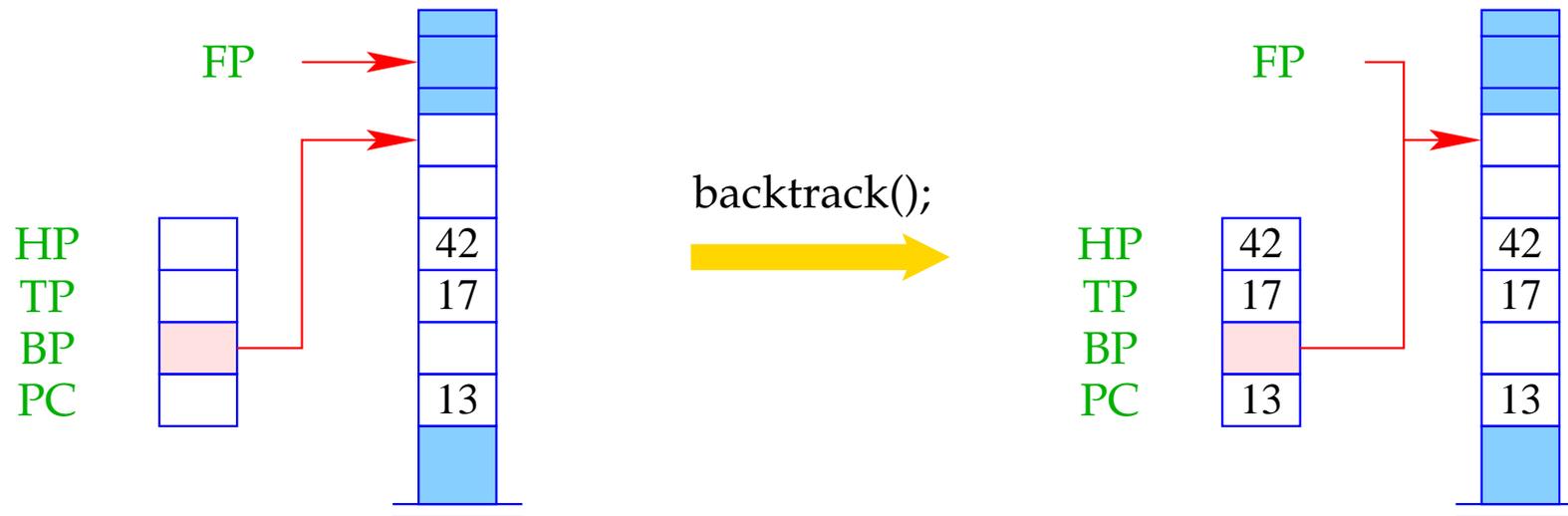
$$\begin{aligned}\text{posCont} &\equiv S[\text{FP}] \\ \text{FPold} &\equiv S[\text{FP} - 1] \\ \text{HPold} &\equiv S[\text{FP} - 2] \\ \text{TPold} &\equiv S[\text{FP} - 3] \\ \text{BPold} &\equiv S[\text{FP} - 4] \\ \text{negCont} &\equiv S[\text{FP} - 5]\end{aligned}$$

for the corresponding addresses.

Remark:

Occurrence on the **left** \equiv saving the register
Occurrence on the **right** \equiv restoring the register

Calling the run-time function `void backtrack()` yields:



```
void backtrack() {  
    FP = BP; HP = HPold;  
    reset (TPold, TP);  
    TP = TPold; PC = negCont;  
}
```

where the run-time function `reset()` undoes the bindings of variables established **since** the backtrack point.

32.2 Resetting Variables

Idea:

- The variables which have been created since the last backtrack point can be removed together with their bindings by popping the heap !!! :-)
- This works fine if **younger** variables always point to **older** objects.
- Bindings of **old** variables to younger objects, though, must be reset **manually** :-(
- These are therefore recorded in the trail.

Functions `void trail(ref u)` and `void reset (ref y, ref x)` can thus be implemented as:

```
void trail (ref u) {
    if (u < S[BP-2]) {
        TP = TP+1;
        T[TP] = u;
    }
}

void reset (ref x, ref y) {
    for (ref u=y; x<u; u--)
        H[T[u]] = (R,T[u]);
}
```

Here, `S[BP-2]` represents the heap pointer when creating the last backtrack point.

32.3 Wrapping it Up

Assume that the predicate q/k is defined by the clauses r_1, \dots, r_f ($f > 1$).

We provide code for:

- **setting** up the backtrack point;
- successively **trying** the alternatives;
- **deleting** the backtrack point.

This means:

```

codeP rr = q/k : setbtp
                try A1
                ...
                try Af-1
                delbtp
                jump Af
A1 : codeC r1
    ...
Af : codeC rf

```

Note:

- We delete the backtrack point **before** the last alternative **:-)**
- We **jump** to the last alternative — never to return to the present frame **:-))**

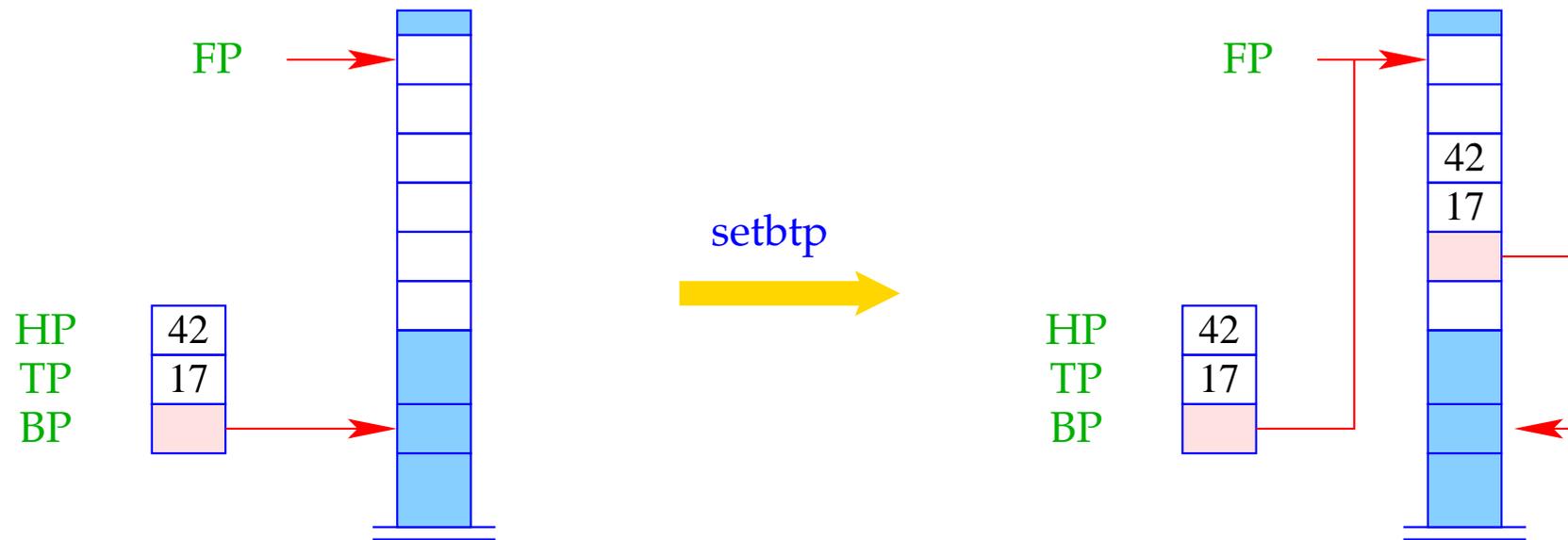
Example:

$$\begin{aligned}s(X) &\leftarrow t(\bar{X}) \\s(X) &\leftarrow \bar{X} = a\end{aligned}$$

The translation of the predicate s yields:

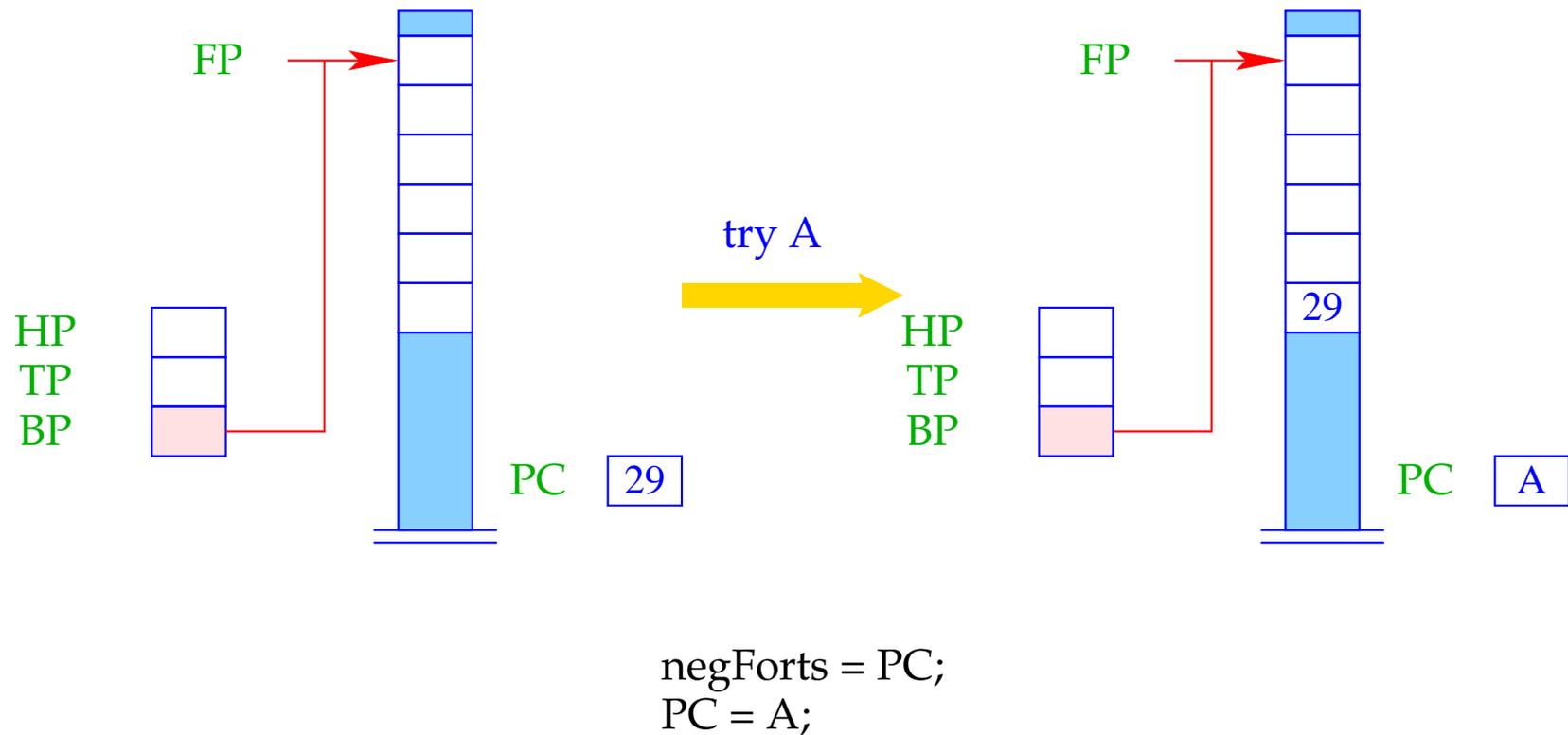
s/1:	setbtp	A:	pushenv 1	B:	pushenv 1
	try A		mark C		putref 1
	delbtp		putref 1		uatom a
	jump B		call t/1		popenv
		C:	popenv		

The instruction `setbtp` saves the registers `HP`, `TP`, `BP`:

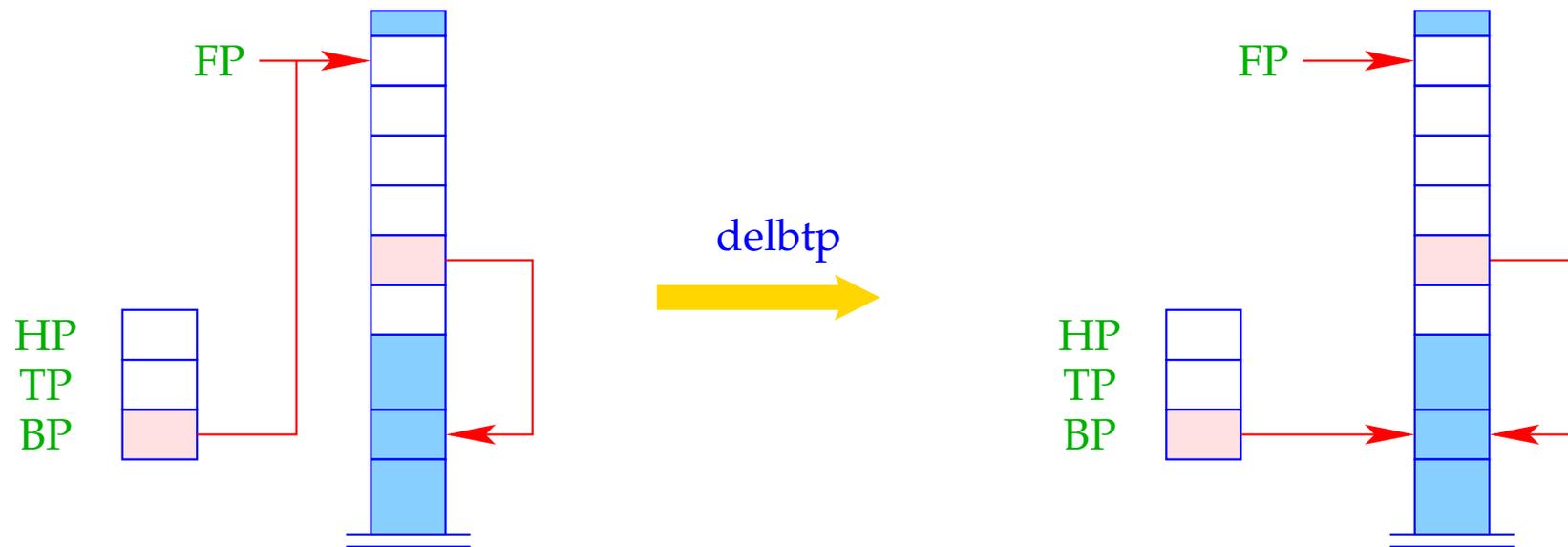


HPold = HP;
TPold = TP;
BPold = BP;
BP = FP;

The instruction `try A` tries the alternative at address `A` and updates the negative continuation address to the current `PC`:



The instruction `delbtp` restores the old backtrace pointer:



$BP = BP_{old};$

32.4 Popping of Stack Frames

Recall the translation scheme for clauses:

$$\begin{aligned} \text{code}_C r &= \text{pushenv } m \\ &\quad \text{code}_G g_1 \rho \\ &\quad \dots \\ &\quad \text{code}_G g_n \rho \\ &\quad \text{popenv} \end{aligned}$$

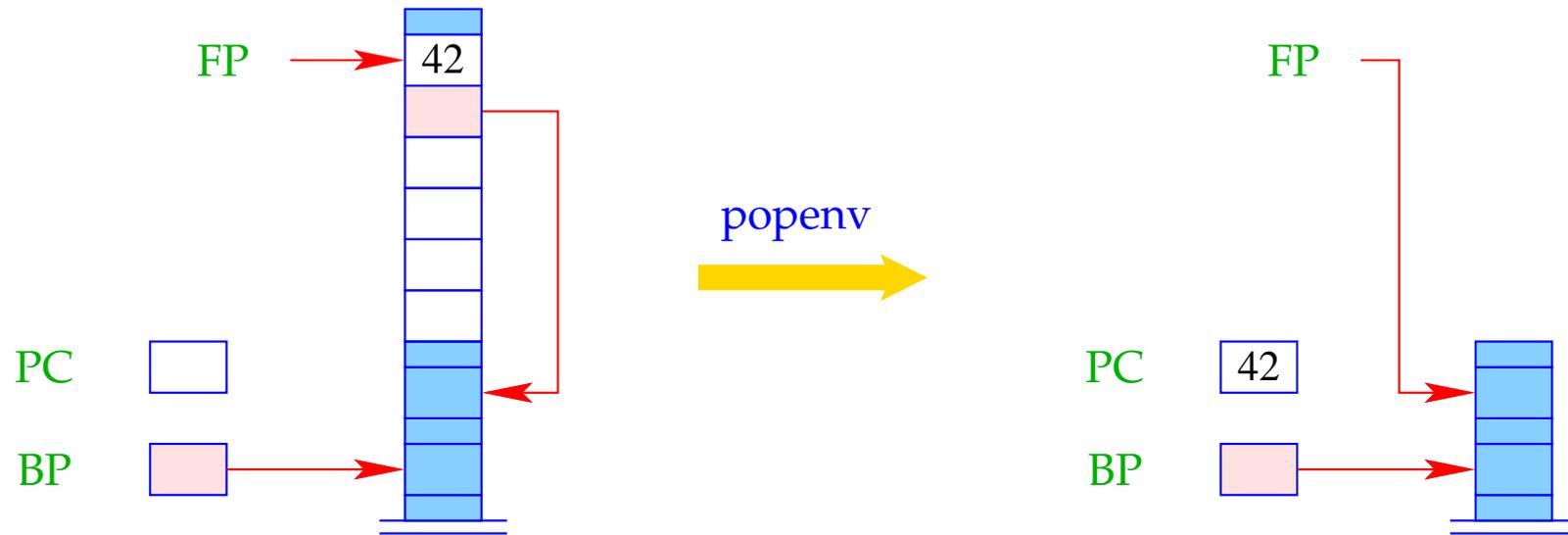
The present stack frame can be **popped** ...

- if the applied clause was the **last** (or **only**); and
- if all goals in the body are definitely **finished**.

\implies the backtrack point is **older** :-)

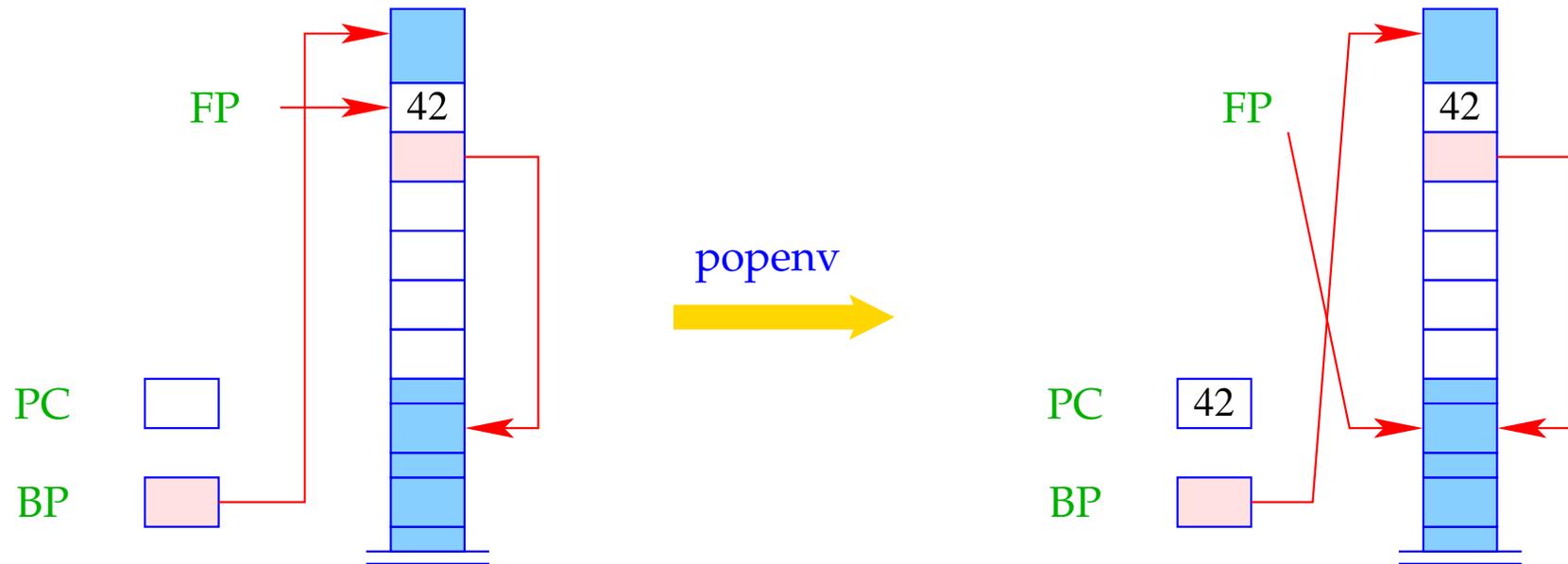
\implies **FP > BP**

The instruction `popenv` restores the registers `FP` and `PC` and possibly pops the stack frame:



```
if (FP > BP) SP = FP - 6;  
PC = posCont;  
FP = FPold;
```

Warning: `popenv` may fail to de-allocate the frame !!!



```

if (FP > BP) SP = FP - 6;
PC = posCont;
FP = FPold;

```

If popping the stack frame fails, new data are allocated on top of the stack. When returning to the frame, the locals still can be accessed through the FP :-))

33 Queries and Programs

The translation of a program: $p \equiv rr_1 \dots rr_h ? g$
consists of:

- an instruction `no` for failure;
- code for evaluating the query `g`;
- code for the predicate definitions rr_i .

Preceding query evaluation:

- \implies initialization of registers
- \implies allocation of space for the globals

Succeeding query evaluation:

- \implies returning the values of globals

```

code p =      init A
              pushenv d
              code_G g ρ
              halt d
              A: no
              code_P rr_1
              ...
              code_P rr_h

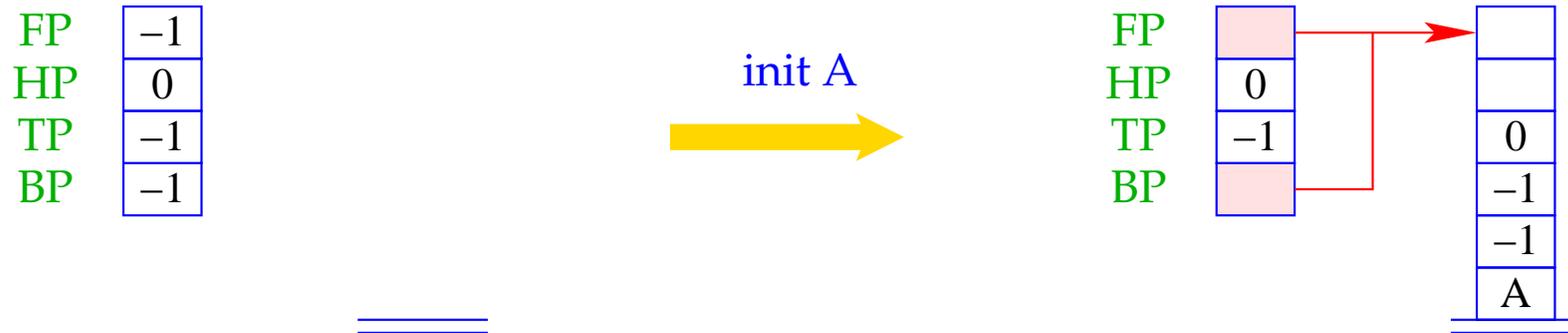
```

where $free(g) = \{X_1, \dots, X_d\}$ and ρ is given by $\rho X_i = i$.

The instruction `halt d ...`

- ... terminates the program execution;
- ... returns the bindings of the d globals;
- ... causes backtracking — if demanded by the user :-)

The instruction `init A` is defined by:



BP = FP = SP = 5;
S[0] = A;
S[1] = S[2] = -1;
S[3] = 0;
BP = FP;

At address "A" for a failing goal we have placed the instruction `no` for printing `no` to the standard output and halt :-)

The Final Example:

$$\begin{array}{lll}
 t(X) \leftarrow \bar{X} = b & q(X) \leftarrow s(\bar{X}) & s(X) \leftarrow \bar{X} = a \\
 p \leftarrow q(X), t(\bar{X}) & s(X) \leftarrow t(\bar{X}) & ? \quad p
 \end{array}$$

The translation yields:

	init N		popenv	q/1:	pushenv 1	E:	pushenv 1
	pushenv 0	p/0:	pushenv 1		mark D		mark G
	mark A		mark B		putref 1		putref 1
	call p/0		putvar 1		call s/1		call t/1
A:	halt 0		call q/1	D:	popenv	G:	popenv
N:	no	B:	mark C	s/1:	setbtp	F:	pushenv 1
t/1:	pushenv 1		putref 1		try E		putref 1
	putref 1		call t/1		delbtp		uatom a
	uatom b	C:	popenv		jump F		popenv

34 Last Call Optimization

Consider the app predicate from the beginning:

$$\text{app}(X, Y, Z) \leftarrow X = [], Y = Z$$
$$\text{app}(X, Y, Z) \leftarrow X = [H|X'], Z = [H|Z'], \text{app}(X', Y, Z')$$

We observe:

- The recursive call occurs in the **last** goal of the clause.
- Such a goal is called **last call**.

\implies we try to evaluate it in the **current** stack frame !!!

\implies after (successful) completion, we will not return to the current caller !!!

Consider a clause r :
 with m locals where
 code_G :

$p(X_1, \dots, X_k) \leftarrow g_1, \dots, g_n$
 $g_n \equiv q(t_1, \dots, t_h)$. The interplay between code_C and

$\text{code}_C r =$

```

pushenv m
code_G g1 ρ
...
code_G gn-1 ρ
mark B
code_A t1 ρ
...
code_A th ρ
call q/h
B : popenv
  
```

Replacement:	mark B	\implies	lastmark
	call q/h; popenv	\implies	lastcall q/h m

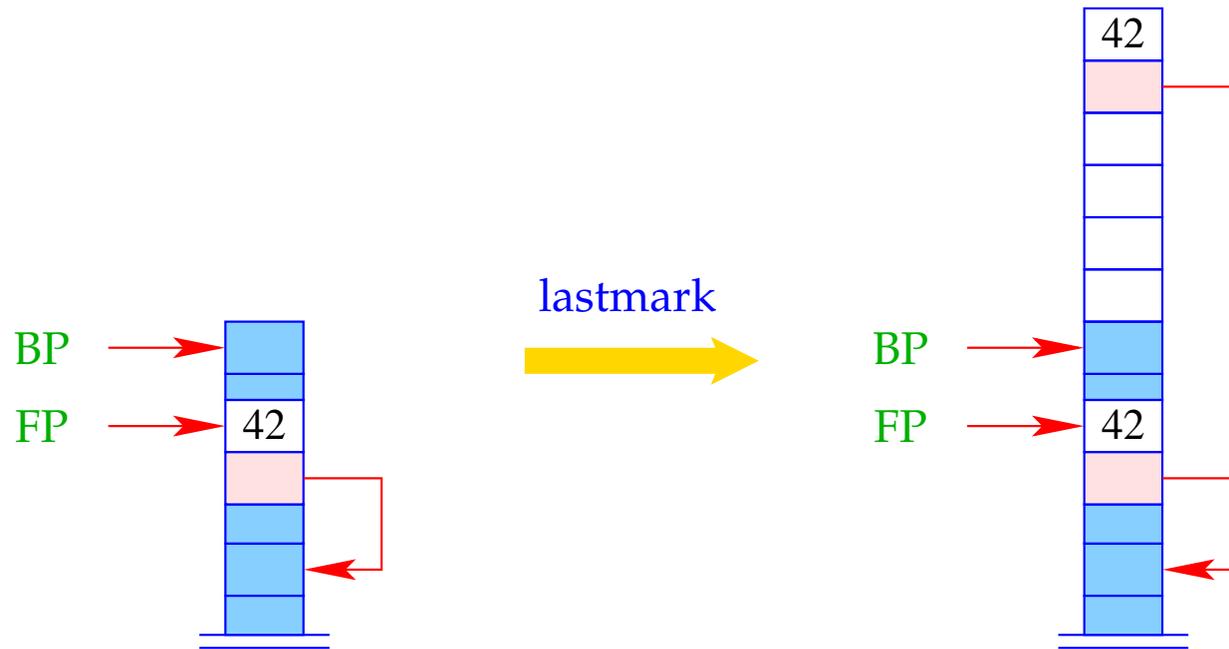
Consider a clause r : $p(X_1, \dots, X_k) \leftarrow g_1, \dots, g_n$
 with m locals where $g_n \equiv q(t_1, \dots, t_h)$. The interplay between code_C and code_G :

$\text{code}_C r =$ $\text{pushenv } m$
 $\text{code}_G g_1 \rho$
 ...
 $\text{code}_G g_{n-1} \rho$
 lastmark
 $\text{code}_A t_1 \rho$
 ...
 $\text{code}_A t_h \rho$
 $\text{lastcall } q/h \ m$

Replacement:	$\text{mark } B$	\implies	lastmark
	$\text{call } q/h; \text{popenv}$	\implies	$\text{lastcall } q/h \ m$

If the current clause is not **last** or the g_1, \dots, g_{n-1} have created backtrack points, then **FP** \leq **BP** :-)

Then **lastmark** creates a new frame but stores a reference to the **predecessor**:



```

if (FP  $\leq$  BP) {
    SP = SP + 6;
    S[SP] = posCont; S[SP-1] = FPold;
}

```

If **FP** $>$ **BP** then **lastmark** does nothing :-)

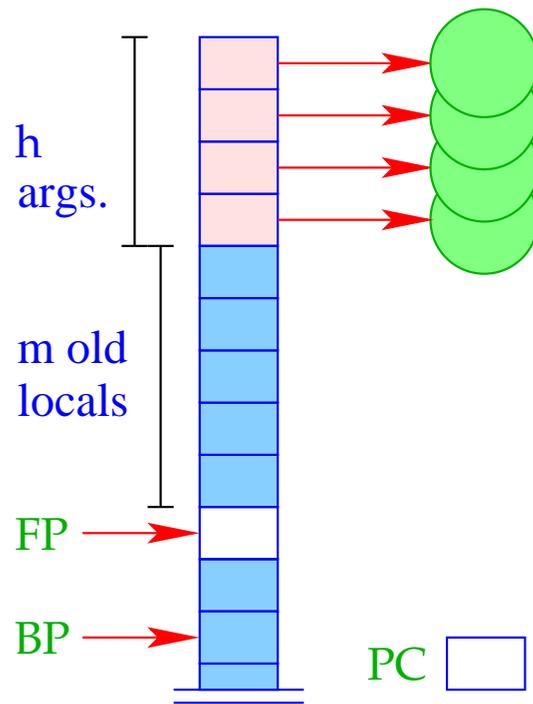
If $FP \leq BP$, then `lastcall q/h m` behaves like a normal `call q/h`.

Otherwise, the current stack frame is re-used. This means that:

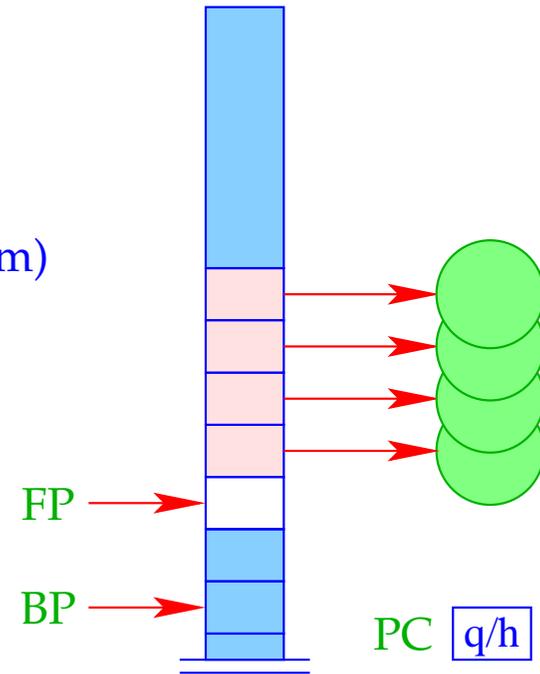
- the cells $S[FP+1], S[FP+2], \dots, S[FP+h]$ receive the new values and
- `q/h` can be jumped to `:-)`

```
lastcall q/h m = if (FP ≤ BP) call q/h;
                else {
                    move m h;
                    jump q/h;
                }
```

The difference between the old and the new addresses of the parameters `m` just equals the number of the `local variables` of the current clause `:-))`



lastcall ($q/h, m$)



Example:

Consider the clause:

$$a(X, Y) \leftarrow f(\bar{X}, X_1), a(\bar{X}_1, \bar{Y})$$

The last-call optimization for `codeC r` yields:

	mark A	A:	lastmark
pushenv 3	putref 1		putref 3
	putvar 3		putref 2
	call f/2		lastcall a/2 3

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The last-call optimization for `codeC r` yields:

	mark A	A: lastmark
pushenv 3	putref 1	putref 3
	putvar 3	putref 2
	call f/2	lastcall a/2 3

Note:

If the clause is **last** and the last literal is the **only one**, we can skip **lastmark** and can replace **lastcall q/h m** with the sequence **move m n; jump p/n :-))**

Example:

Consider the **last** clause of the app predicate:

$$\text{app}(X, Y, Z) \leftarrow \bar{X} = [H|X'], \bar{Z} = [\bar{H}|Z'], \text{app}(\bar{X}', \bar{Y}, \bar{Z}')$$

Here, the last call is the **only one** :-). Consequently, we obtain:

A: pushenv 6			uref 4	bind
putref 1	B: putvar 4		son 2	E: putref 5
ustruct [[]]/2 B	putvar 5		uvar 6	putref 2
son 1	putstruct [[]]/2		up E	putref 6
uvar 4	bind	D: check 4		move 6 3
son 2	C: putref 3	putref 4		jump app/3
uvar 5	ustruct [[]]/2 D	putvar 6		
up C	son 1	putstruct [[]]/2		

35 Trimming of Stack Frames

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- Order local variables according to their **life times**;
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Consider the clause:

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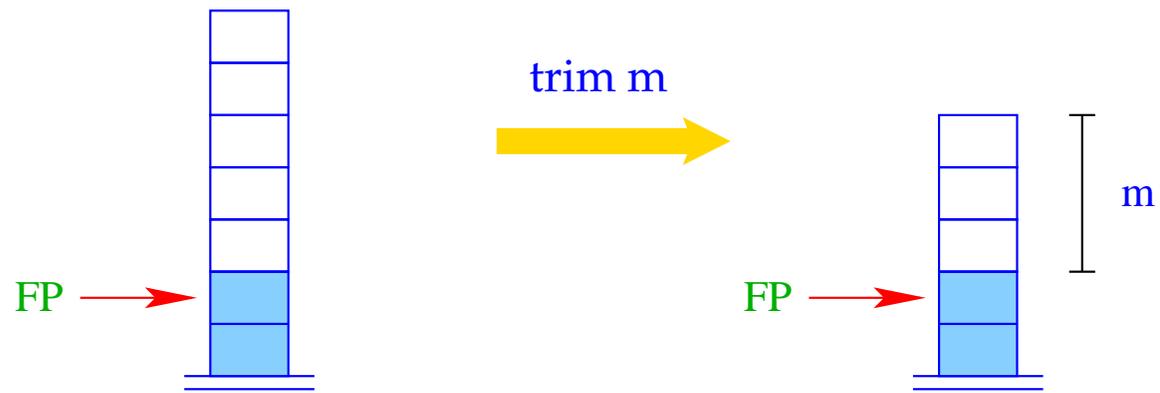
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After the query $p_2(\bar{X}_1, X_2)$, variable X_1 is dead.

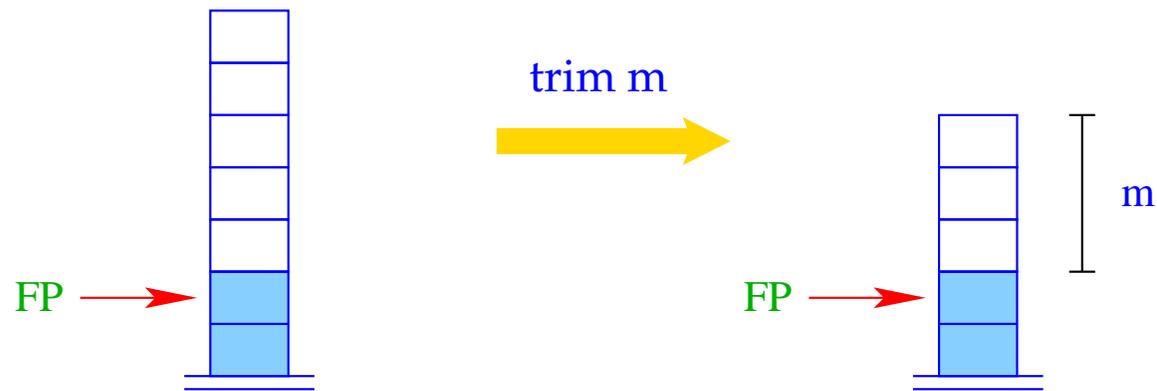
After the query $p_3(\bar{X}_2, X_3)$, variable X_2 is dead **:-)**

After every non-last goal with dead variables, we insert the instruction `trim` :



```
if (FP ≥ BP)
    SP = FP + m;
```

After every non-last goal with dead variables, we insert the instruction `trim` :



```
if (FP ≥ BP)
    SP = FP + m;
```

The dead locals can only be popped if no new backtrack point has been allocated :-)

Example (continued):

$$a(X, Z) \leftarrow p_1(\bar{X}, X_1), p_2(\bar{X}_1, X_2), p_3(\bar{X}_2, X_3), p_4(\bar{X}_3, \bar{Z})$$

Ordering of the variables:

$$\rho = \{X \mapsto 1, Z \mapsto 2, X_3 \mapsto 3, X_2 \mapsto 4, X_1 \mapsto 5\}$$

The resulting code:

pushenv 5	A:	mark B	mark C	lastmark
mark A		putref 5	putref 4	putref 3
putref 1		putvar 4	putvar 3	putref 2
putvar 5		call p ₂ /2	call p ₃ /2	lastcall p ₄ /2 3
call p ₁ /2	B:	trim 4	C:	trim 3