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# Program Optimization

*TU München*

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# Organization

**Dates:** **Lecture:** Monday, 12-14  
Tuesday, 12-14  
**Tutorials:** Friday, 12-14  
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**Material:** slides, **recording** :-)  
**simulator environment**

**Grades:**

- Bonus for homeworks
- written exam

# Proposed Content:

## 1. Avoiding redundant computations

- available expressions
- constant propagation/array-bound checks
- code motion

## 2. Replacing expensive with cheaper computations

- peep hole optimization
- inlining
- reduction of strength

...

### 3. Exploiting Hardware

- Instruction selection
- Register allocation
- Scheduling
- Memory management

# 0 Introduction

Observation 1: Intuitive programs often are inefficient.

Example:

```
void swap (int i, int j) {  
    int t;  
    if (a[i] > a[j]) {  
        t = a[j];  
        a[j] = a[i];  
        a[i] = t;  
    }  
}
```

## Inefficiencies:

- Addresses  $a[i]$ ,  $a[j]$  are computed three times :-)
- Values  $a[i]$ ,  $a[j]$  are loaded twice :-)

## Improvement:

- Use a pointer to traverse the array  $a$ ;
- store the values of  $a[i]$ ,  $a[j]$ !

```
void swap (int *p, int *q) {  
    int t, ai, aj;  
    ai = *p; aj = *q;  
    if (ai > aj) {  
        t = aj;  
        *q = ai;  
        *p = t;    // t can also be  
    }            // eliminated!  
}
```

## Observation 2:

Higher programming languages (even C :-)) abstract from hardware and efficiency.

It is up to the compiler to adapt *intuitively* written program to hardware.

## Examples:

- ... Filling of delay slots;
- ... Utilization of special instructions;
- ... Re-organization of memory accesses for better cache behavior;
- ... Removal of (useless) overflow/range checks.



## Observation 3:

Programm-Improvements need not always be correct :-)

## Example:

$$y = f() + f(); \quad \Longrightarrow \quad y = 2 * f();$$

Idea: Save second evaluation of  $f()$  ...

## Observation 3:

Programm-Improvements need not always be correct :-)

## Example:

$$y = f() + f(); \quad \Longrightarrow \quad y = 2 * f();$$

**Idea:** Save the second evaluation of  $f()$  ???

**Problem:** The second evaluation may return a result different from the first; (e.g., because  $f()$  reads from the input :-)

## Consequences:

- ⇒ Optimizations have **assumptions**.
- ⇒ The **assumption** must be:
  - formalized,
  - checked :-)
- ⇒ It must be proven that the optimization is **correct**, i.e., preserves the **semantics !!!**

## Observation 4:

Optimization techniques depend on the **programming language**:

- which inefficiencies occur;
- how analyzable programs are;
- how difficult/impossible it is to prove correctness ...

**Example:**          **Java**

## Unavoidable Inefficiencies:

- \* Array-bound checks;
- \* Dynamic method invocation;
- \* Bombastic object organization ...

## Analyzability:

- + no pointer arithmetic;
- + no pointer into the stack;
- dynamic class loading;
- reflection, exceptions, threads, ...

## Correctness proofs:

- + more or less well-defined semantics;
- features, features, features;
- libraries with changing behavior ...

... in this course:

a simple **imperative** programming language with:

- variables // registers
- $R = e;$  // assignments
- $R = M[e];$  // loads
- $M[e_1] = e_2;$  // stores
- if ( $e$ )  $s_1$  else  $s_2$  // conditional branching
- goto  $L;$  // no loops :-)

## Note:

- For the beginning, we omit procedures :-)
- External procedures are taken into account through a statement  $f()$  for an unknown procedure  $f$ .
  - ⇒ intra-procedural
  - ⇒ kind of an intermediate language in which (almost) everything can be translated.

Example: `swap ( )`



```

0 :   A1 = A0 + 1 * i;           //   A0 == &a
1 :   R1 = M[A1];               //   R1 == a[i]
2 :   A2 = A0 + 1 * j;
3 :   R2 = M[A2];               //   R2 == a[j]
4 :   if (R1 > R2) {
5 :       A3 = A0 + 1 * j;
6 :       t = M[A3];
7 :       A4 = A0 + 1 * j;
8 :       A5 = A0 + 1 * i;
9 :       R3 = M[A5];
10 :      M[A4] = R3;
11 :      A6 = A0 + 1 * i;
12 :      M[A6] = t;
      }

```

Optimization 1:  $1 * R \implies R$

Optimization 2: Reuse of subexpressions

$$A_1 == A_5 == A_6$$

$$A_2 == A_3 == A_4$$

$$M[A_1] == M[A_5]$$

$$M[A_2] == M[A_3]$$

$$R_1 == R_3$$

By this, we obtain:

$$A_1 = A_0 + i;$$

$$R_1 = M[A_1];$$

$$A_2 = A_0 + j;$$

$$R_2 = M[A_2];$$

if  $(R_1 > R_2)$  {

$$t = R_2;$$

$$M[A_2] = R_1;$$

$$M[A_1] = t;$$

}

## Optimization 3: Contraction of chains of assignments :-)

Gain:

|       | before | after |
|-------|--------|-------|
| +     | 6      | 2     |
| *     | 6      | 0     |
| load  | 4      | 2     |
| store | 2      | 2     |
| >     | 1      | 1     |
| =     | 6      | 2     |

# 1 Removing superfluous computations

## 1.1 Repeated computations

Idea:

If the same value is computed **repeatedly**, then

- **store** it after the first computation;
- replace every further computation through a **look-up!**
- ⇒ Availability of expressions
- ⇒ Memoization

**Problem:** Identify repeated computations!

**Example:**

$$\begin{array}{l} z = 1; \\ y = M[17]; \\ A : x_1 = y + z; \\ \quad \dots \\ B : x_2 = y + z; \end{array}$$

## Note:

$B$  is a repeated computation of the value of  $y + z$ , if:

(1)  $A$  is **always** executed **before**  $B$ ; and

(2)  $y$  and  $z$  at  $B$  have the same values as at  $A$  :-)

⇒ We need:

→ an operational semantics :-)

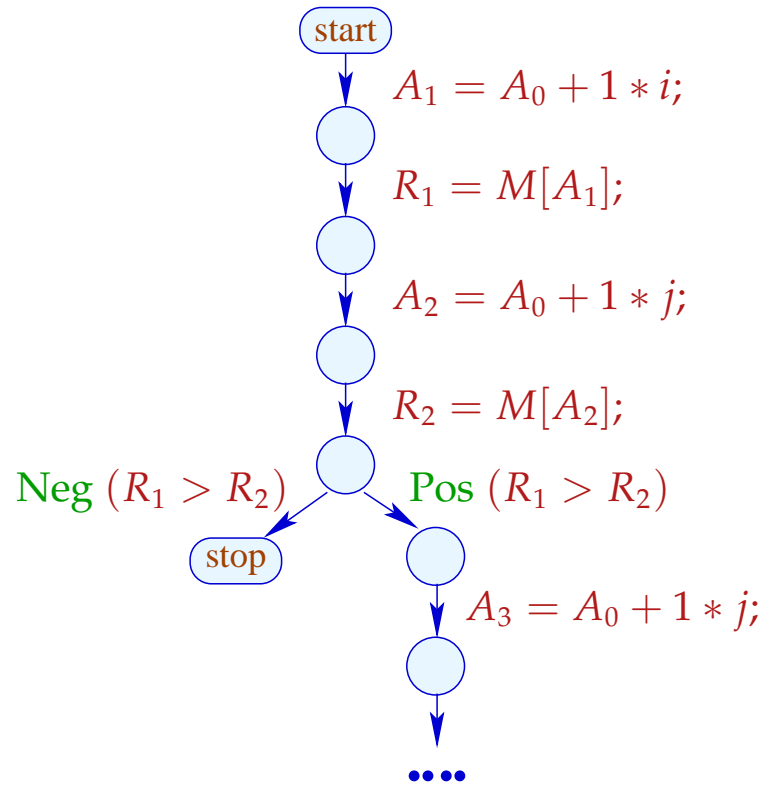
→ a method which identifies at least **some** repeated computations ...

# Background 1: An Operational Semantics

we choose a **small-step** operational approach.

Programs are represented as **control-flow graphs**.

In the example:





Thereby, represent:

|        |                     |
|--------|---------------------|
| vertex | program point       |
| start  | programm start      |
| stop   | program exit        |
| edge   | step of computation |

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|        |                     |
|--------|---------------------|
| vertex | program point       |
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Edge Labelings:

**Test :** Pos ( $e$ ) or Neg ( $e$ )

**Assignment :**  $R = e;$

**Load :**  $R = M[e];$

**Store :**  $M[e_1] = e_2;$

**Nop :** ;

Computations follow **paths**.

Computations transform the current **state**

$$s = (\rho, \mu)$$

where:

|   |                       |
|---|-----------------------|
| $\rho : \text{Vars} \rightarrow \mathbf{int}$ | contents of registers |
| $\mu : \mathbb{N} \rightarrow \mathbf{int}$   | contents of storage   |

Every **edge**  $k = (u, lab, v)$  defines a **partial transformation**

$$\llbracket k \rrbracket = \llbracket lab \rrbracket$$

of the state: