

Proof:

Ad (1):

Every unknown  $x_i$  may change its value at most  $h$  times :-)

Each time, the list  $I[x_i]$  is added to  $W$ .

Thus, the total number of evaluations is:

$$\begin{aligned} &\leq n + \sum_{i=1}^n (h \cdot \#(I[x_i])) \\ &= n + h \cdot \sum_{i=1}^n \#(I[x_i]) \\ &= n + h \cdot \sum_{i=1}^n \#(Dep f_i) \\ &\leq h \cdot \sum_{i=1}^n (1 + \#(Dep f_i)) \\ &= h \cdot N \end{aligned}$$

Ad (2):

We only consider the assertion for monotonic  $f_i$ .

Let  $D_0$  denote the least solution. We show:

- $D_0[x_i] \supseteq D[x_i]$  (all the time)
- $D[x_i] \not\models f_i \text{ eval} \implies x_i \in W$  (at exit of the loop body)
- On termination, the algo returns a solution  $:-))$

## Discussion:

- In the example, fewer evaluations of right-hand sides are required than for RR-iteration :-)
- The algo also works for non-monotonic  $f_i$  :-)
- For monotonic  $f_i$ , the algo can be simplified:

$$\boxed{D[x_i] = D[x_i] \sqcup t;} \implies \boxed{D[x_i] = t;}$$

- In presence of **widening**, we replace:

$$\boxed{D[x_i] = D[x_i] \sqcup t;} \implies \boxed{D[x_i] = D[x_i] \sqcup t;}$$

- In presence of **Narrowing**, we replace:

$$\boxed{D[x_i] = D[x_i] \sqcup t;} \implies \boxed{D[x_i] = D[x_i] \sqcap t;}$$

## Warning:

- The algorithm relies on explicit dependencies among the unknowns.

So far in our applications, these were **obvious**. This need not always be the case :-)

- We need some **strategy** for **extract** which determines the next unknown to be evaluated.
- It would be ingenious if we always evaluated **first** and then accessed the result ... :-)

⇒ recursive evaluation ...

## Idea:

- If during evaluation of  $f_i$ , an unknown  $x_j$  is accessed,  $x_j$  is first solved recursively. Then  $x_i$  is added to  $I[x_j]$  :-)

$\text{eval } x_i \ x_j = \text{solve } x_j;$

$I[x_j] = I[x_j] \cup \{x_i\};$

$D[x_j];$

- In order to prevent recursion to descend infinitely, a set *Stable* of unknown is maintained for which *solve* just looks up their values :-)

Initially,  $\textit{Stable} = \emptyset \dots$

## The Function solve :

```
solve  $x_i$  = if ( $x_i \notin Stable$ ) {  
     $Stable = Stable \cup \{x_i\}$ ;  
     $t = f_i(\text{eval } x_i)$ ;  
    if ( $t \not\subseteq D[x_i]$ ) {  
         $W = I[x_i]; \quad I[x_i] = \emptyset$ ;  
         $D[x_i] = D[x_i] \sqcup t$ ;  
         $Stable = Stable \setminus W$ ;  
        app solve  $W$ ;  
    }  
}
```



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## Example:

Consider our standard example:

$$x_1 \supseteq \{a\} \cup x_3$$

$$x_2 \supseteq x_3 \cap \{a, b\}$$

$$x_3 \supseteq x_1 \cup \{c\}$$

A trace of the fixpoint algorithm then looks as follows: