

## Example

**type** tree  $\alpha$  = Leaf | Node  $\alpha$  (tree  $\alpha$ ) (tree  $\alpha$ )

**map** = **fun**  $f$   $\rightarrow$  **fun**  $t$   $\rightarrow$  **match**  $t$  **with** Leaf  $\rightarrow$  Leaf  
| Node  $x$   $l$   $r$   $\rightarrow$  **let**  $l'$  = **map**  $f$   $l$   
 $r'$  = **map**  $f$   $r$   
**in** Node ( $f$   $x$ )  $l'$   $r'$

**foldl** = **fun**  $f$   $\rightarrow$  **fun**  $a$   $\rightarrow$  **fun**  $t$   $\rightarrow$  **match**  $t$  **with** Leaf  $\rightarrow$   $a$   
| Node  $x$   $l$   $r$   $\rightarrow$  **let**  $a'$  = **foldl**  $f$   $a$   $l$   
**in** **foldl**  $f$  ( $f$   $a'$   $x$ )  $r$

```
to_list' = fun a → fun t → match t with Leaf → a
          | Node x t1 t2 → let a' = to_list' a t2
                               in to_list' (x :: a') t1
```

```
to_list = to_list' []
```

```
from_list = fun l →
            match l with [] → Leaf
            | :: z → (match z with (x, xs) →
                       Node x Leaf (from_list xs))
```

## Warning:

Not every natural equation is valid:

$$\begin{aligned} \text{comp to\_list from\_list} &= \text{id} \\ \text{comp from\_list to\_list} &\neq \text{id} \\ \text{comp to\_list (map } f) &= \text{comp (map } f) \text{ to\_list} \\ \text{comp from\_list (map } f) &= \text{comp (map } f) \text{ from\_list} \\ \text{comp (foldl } f \ a) \text{ to\_list} &= \text{foldl } f \ a \\ \text{comp (foldl } f \ a) \text{ from\_list} &= \text{foldl } f \ a \end{aligned}$$

In this case, there is even a `rev`:

```
rev = fun t →  
      match t with Leaf → Leaf  
      | Node x t1 t2 → let s1 = rev t1  
                          s2 = rev t2  
                          in Node x s2 s1
```

```
comp to_list rev = comp rev to_list  
comp from_list rev ≠ comp rev from_list
```

## 4.6 CBN vs. CBV: Strictness Analysis

### Problem:

- Programming languages such as **Haskell** evaluate expressions for **let**-defined variables and actual parameters not before their values are accessed.
- This allows for an elegant treatment of (possibly) infinite lists of which only small initial segments are required for computing the result :-)
- Delaying evaluation by default incurs, though, a non-trivial overhead ...

## Example

`from` = **fun**  $n$   $\rightarrow$   $n ::$  `from` ( $n + 1$ )

`take` = **fun**  $k$   $\rightarrow$  **fun**  $s$   $\rightarrow$  **if**  $k \leq 0$  **then** `[]`  
**else** **match**  $s$  **with** `[]`  $\rightarrow$  `[]`  
 $|$   $z ::$   $z$   $\rightarrow$  **match**  $z$  **with**  $(x, xs)$   $\rightarrow$   
 $x ::$  `take` ( $k - 1$ )  $xs$

Then CBN yields:

take 5 (from 0) = [0, 1, 2, 3, 4]

— whereas evaluation with CBV does not terminate !!!

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On the other hand, for CBN, tail-recursive functions may require non-constant space ???

```
fac2 = fun x → fun a → if x ≤ 0 then a
                        else fac2 (x - 1) (a · x)
```



## Discussion:

- The multiplications are collected in the accumulating parameter through nested closures.
- Only when the value of a call `fac2 x 1` is accessed, this dynamic data-structure is evaluated.
- Instead, the accumulating parameter should have been passed directly by-value !!!
- This is the goal of the following optimization ...

## Simplification:

- At first, we rule out data-structures, higher-order functions, and local function definitions.
- We introduce an unary operator # which forces the evaluation of a variable.
- Goal of the transformation is to place # at as many places as possible ...

## Simplification:

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$$e ::= c \mid x \mid e_1 \square_2 e_2 \mid \square_1 e \mid f e_1 \dots e_k \mid \mathbf{if} e_0 \mathbf{then} e_1 \mathbf{else} e_2 \\ \mid \mathbf{let} r_1 = e_1 \mathbf{in} e$$
$$r ::= x \mid \#x$$
$$d ::= f x_1 \dots x_k = e$$
$$p ::= \mathbf{letrec} \mathbf{and} d_1 \dots \mathbf{and} d_n \mathbf{in} e$$

## Idea:

- Describe a  $k$ -ary function

$$f : \mathbf{int} \rightarrow \dots \rightarrow \mathbf{int}$$

by a function

$$\llbracket f \rrbracket^\# : \mathbb{B} \rightarrow \dots \rightarrow \mathbb{B}$$

- $0$  means: evaluation does definitely not terminate.
- $1$  means: evaluation may terminate.
- $\llbracket f \rrbracket^\# 0 = 0$  means: If the function call returns a value, then the evaluation of the argument must have terminated and returned a value.

$\implies$   $f$  is **strict**.

## Idea (cont.):

- We determine the abstract semantics of all functions :-)
- For that, we put up a system of equations ...

## Auxiliary Function:

$$\begin{aligned} \llbracket e \rrbracket^\# & : (Vars \rightarrow \mathbb{B}) \rightarrow \mathbb{B} \\ \llbracket c \rrbracket^\# \rho & = 1 \\ \llbracket x \rrbracket^\# \rho & = \rho x \\ \llbracket \square_1 e \rrbracket^\# \rho & = \llbracket e \rrbracket^\# \rho \\ \llbracket e_1 \square_2 e_2 \rrbracket^\# \rho & = \llbracket e_1 \rrbracket^\# \rho \wedge \llbracket e_2 \rrbracket^\# \rho \\ \llbracket \mathbf{if} \ e_0 \ \mathbf{then} \ e_1 \ \mathbf{else} \ e_2 \rrbracket^\# \rho & = \llbracket e_0 \rrbracket^\# \rho \wedge (\llbracket e_1 \rrbracket^\# \rho \vee \llbracket e_2 \rrbracket^\# \rho) \\ \llbracket f \ e_1 \ \dots \ e_k \rrbracket^\# \rho & = \llbracket f \rrbracket^\# (\llbracket e_1 \rrbracket^\# \rho) \ \dots \ (\llbracket e_k \rrbracket^\# \rho) \\ \dots & \end{aligned}$$

$$\begin{aligned} \llbracket \mathbf{let} \ x_1 = e_1 \ \mathbf{in} \ e \rrbracket^\# \rho &= \llbracket e \rrbracket^\# (\rho \oplus \{x_1 \mapsto \llbracket e_1 \rrbracket^\# \rho\}) \\ \llbracket \mathbf{let} \ #x_1 = e_1 \ \mathbf{in} \ e \rrbracket^\# \rho &= (\llbracket e_1 \rrbracket^\# \rho) \wedge (\llbracket e \rrbracket^\# (\rho \oplus \{x_1 \mapsto \mathbf{1}\})) \end{aligned}$$

## System of Equations:

$$\llbracket f_i \rrbracket^\# b_1 \dots b_k = \llbracket e_i \rrbracket^\# \{x_j \mapsto b_j \mid j = 1, \dots, k\}, \quad i = 1, \dots, n, b_1, \dots, b_k \in \mathbb{B}$$

- The unknowns of the system of equations are the functions  $\llbracket f_i \rrbracket^\#$  or the individual entries  $\llbracket f_i \rrbracket^\# b_1 \dots b_k$  in the value table.
- All right-hand sides are **monotonic!**
- Consequently, there is a least solution **:-)**
- The complete lattice  $\mathbb{B} \rightarrow \dots \rightarrow \mathbb{B}$  has height  $\mathcal{O}(2^k)$  **:-(**

## Example:

For `fac2`, we obtain:

$$\begin{aligned} \llbracket \text{fac2} \rrbracket^\# b_1 b_2 &= b_1 \wedge (b_2 \vee \\ &\quad \llbracket \text{fac2} \rrbracket^\# b_1 (b_1 \wedge b_2)) \end{aligned}$$

Fixpoint iteration yields:

0	<code>fun x → fun a → 0</code>
1	<code>fun x → fun a → x ∧ a</code>
2	<code>fun x → fun a → x ∧ a</code>

## We conclude:

- The function `fac2` is strict in both arguments, i.e., if evaluation terminates, then also the evaluation of its arguments.
- Accordingly, we transform:

```
fac2 = fun x → fun a → if x ≤ 0 then a
                        else let # x' = x - 1
                                # a' = x · a
                        in fac2 x' a'
```



## Correctness of the Analysis:

- The system of equations is an abstract **denotational** semantics.
- The denotational semantics characterizes the meaning of functions as least solution of the corresponding equations for the concrete semantics.
- For values, the denotational semantics relies on the **complete** partial ordering  $\mathbb{Z}_\perp$ .
- For complete partial orderings, **Kleene's** fixpoint theorem is applicable :-)
- As description relation  $\Delta$  we use:

$$\perp \Delta 0 \quad \text{und} \quad z \Delta 1 \quad \text{für } z \in \mathbb{Z}$$

## Extension: Data-Structures

- Functions may vary in the parts which they require from a data-structure ...

$$\text{hd} = \text{fun } l \rightarrow \text{match } l \text{ with } ::z \rightarrow \\ \text{match } z \text{ with } (x, xs) \rightarrow x$$

- `hd` only accesses the first element of a list.
- `length` only accesses the backbone of its argument.
- `rev` forces the evaluation of the complete argument — given that the result is required completely ...