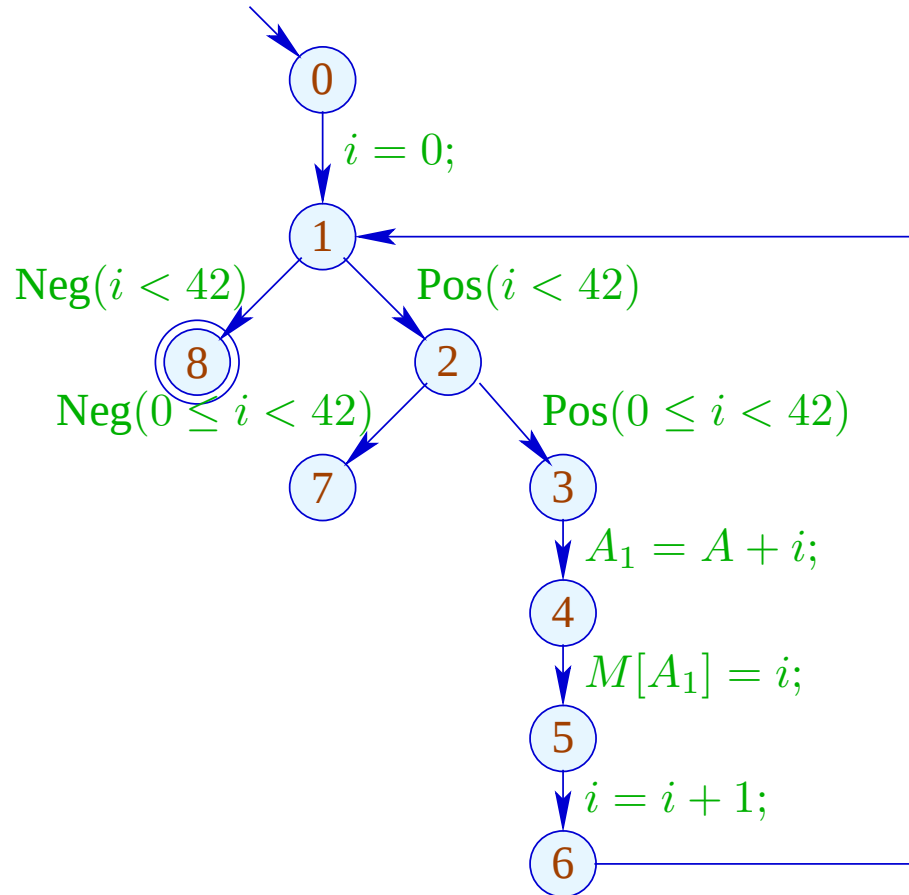


Accelerated Narrowing in the Example:



	0		1		2	
	<i>l</i>	<i>u</i>	<i>l</i>	<i>u</i>	<i>l</i>	<i>u</i>
0	$-\infty$	$+\infty$	$-\infty$	$+\infty$	$-\infty$	$+\infty$
1	0	$+\infty$	0	$+\infty$	0	42
2	0	$+\infty$	0	41	0	41
3	0	$+\infty$	0	41	0	41
4	0	$+\infty$	0	41	0	41
5	0	$+\infty$	0	41	0	41
6	1	$+\infty$	1	42	1	42
7	42	$+\infty$		$\perp$		$\perp$
8	42	$+\infty$	42	$+\infty$	42	42

Discussion:

- **Caveat:** Widening also returns for non-monotonic f_i a solution. Narrowing is only applicable to monotonic f_i !!
- In the example, accelerated narrowing already returns the optimal result :-)
- If the operator $\sqcap$ only allows for finitely many improvements of values, we may execute narrowing until stabilization.
- In case of interval analysis these are at most:

$$\#points \cdot (1 + 2 \cdot \#Vars)$$

1.6 Pointer Analysis

Questions:

- Are two addresses **possibly** equal?
- Are two addresses **definitively** equal?

1.6 Pointer Analysis

Questions:

→ Are two addresses **possibly** equal?

May Alias

→ Are two addresses **definitively** equal?

Must Alias

⇒ **Alias** Analysis

The analyses so far without alias information:

(1) Available Expressions:

- Extend the set $Expr$ of expressions by occurring loads $M[e]$.
- Extend the Effects of Edges:

$$\llbracket x = e; \rrbracket^\# A = (A \cup \{e\}) \setminus Expr_x$$

$$\llbracket x = M[e]; \rrbracket^\# A = (A \cup \{e, M[e]\}) \setminus Expr_x$$

$$\llbracket M[e_1] = e_2; \rrbracket^\# A = (A \cup \{e_1, e_2\}) \setminus Loads$$

(2) Values of Variables:

- Extend the set $Expr$ of expressions by occurring loads $M[e]$.
- Extend the Effects of Edges:

$$\begin{aligned} \llbracket x = M[e]; \rrbracket^\# V e' &= \begin{cases} \{x\} & \text{if } e' = M[e] \\ \emptyset & \text{if } e' = e \\ V e' \setminus \{x\} & \text{otherwise} \end{cases} \\ \llbracket M[e_1] = e_2; \rrbracket^\# V e' &= \begin{cases} \emptyset & \text{if } e' \in \{e_1, e_2\} \\ V e' & \text{otherwise} \end{cases} \end{aligned}$$

(3) Constant Propagation:

- Extend the abstract state by an abstract store M
- Execute accesses to known memory locations!

$$\begin{aligned}
 \llbracket x = M[e]; \rrbracket^\# (D, M) &= \begin{cases} (D \oplus \{x \mapsto M a\}, M) & \text{if} \\ & \llbracket e \rrbracket^\# D = a \sqsubset \top \\ (D \oplus \{x \mapsto \top\}, M) & \text{otherwise} \end{cases} \\
 \llbracket M[e_1] = e_2; \rrbracket^\# (D, M) &= \begin{cases} (D, M \oplus \{a \mapsto \llbracket e_2 \rrbracket^\# D\}) & \text{if} \\ & \llbracket e_1 \rrbracket^\# D = a \sqsubset \top \\ (D, \underline{\top}) & \text{otherwise} \end{cases} \quad \text{where} \\
 \underline{\top} a &= \top \quad (a \in \mathbb{N})
 \end{aligned}$$

Problems:

- Addresses are from $\mathbb{N}$:-(
There are **no infinite** strictly ascending chains, but ...
- Exact addresses at compile-time are **rarely** known :-(
At the same program point, typically different addresses are accessed ...
- Storing at an **unknown** address destroys all information M :-(

 $\implies$ constant propagation fails :-(
 $\implies$ memory accesses/pointers **kill precision** :-(

Simplification:

- We consider pointers to the beginning of **blocks** A which allow indexed accesses $A[i]$:-)
- We ignore well-typedness of the blocks.
- New statements:

$x = \text{new}();$ // allocation of a new block

$x = y[e];$ // indexed read access to a block

$y[e_1] = e_2;$ // indexed write access to a block

- Blocks are possibly infinite :-)
- For simplicity, all pointers point to the beginning of a block.

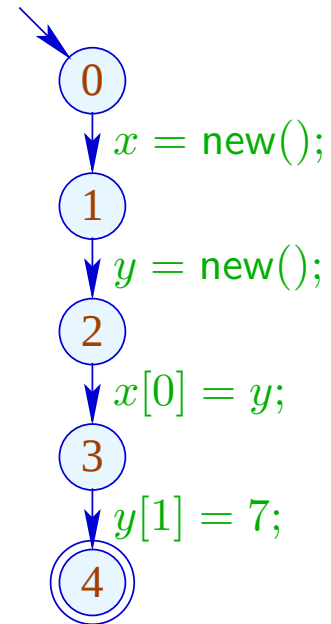
Simple Example:

$x = \text{new}();$

$y = \text{new}();$

$x[0] = y;$

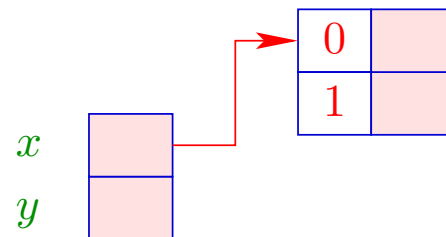
$y[1] = 7;$



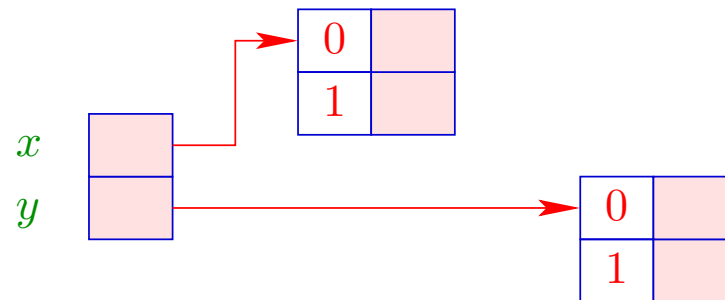
The Semantics:

x	
y	

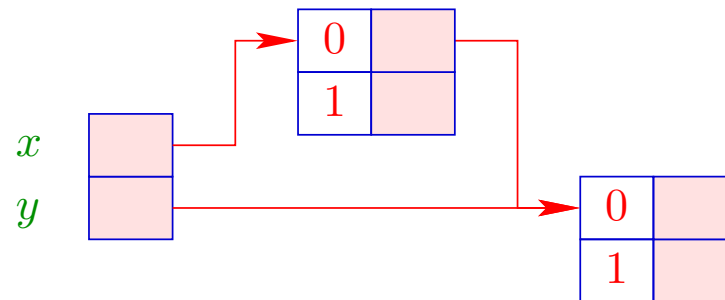
The Semantics:



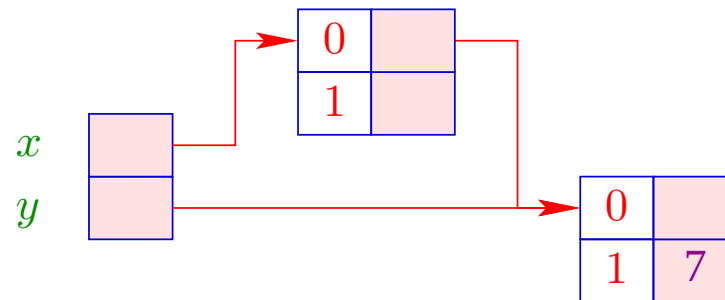
The Semantics:



The Semantics:

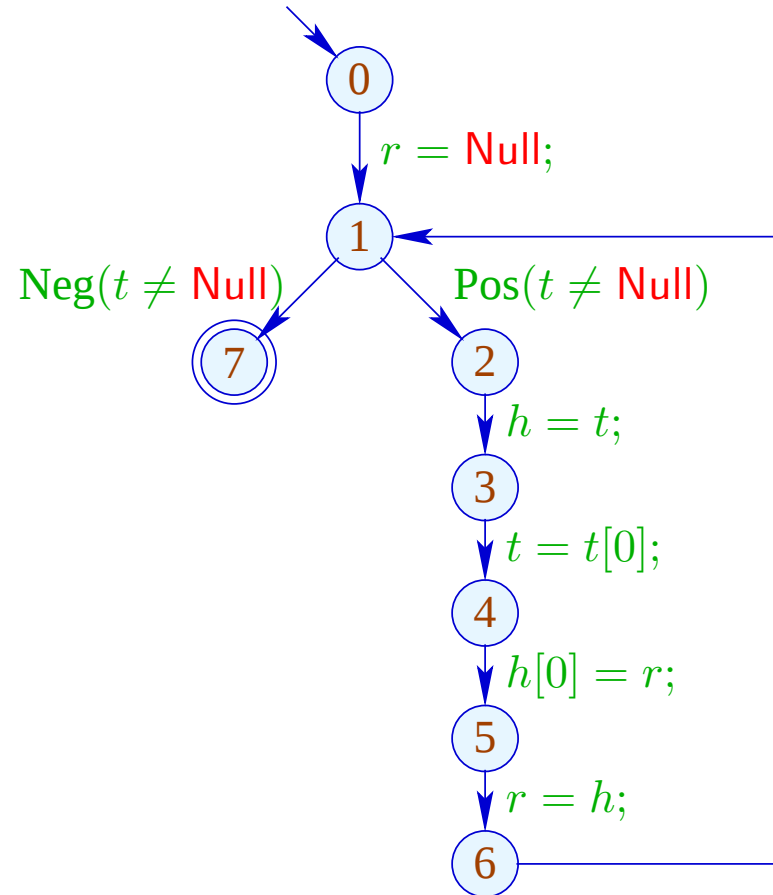


The Semantics:



More Complex Example:

```
r = Null;  
while (t ≠ Null) {  
    h = t;  
    t = t[0];  
    h[0] = r;  
    r = h;  
}
```



Concrete Semantics:

A store consists of a **finite** collection of blocks.

After h new-operations we obtain:

$$Addr_h = \{\text{ref } a \mid 0 \leq a < h\} \quad // \text{ addresses}$$

$$Val_h = Addr_h \cup \mathbb{Z} \quad // \text{ values}$$

$$Store_h = (Addr_h \times \mathbb{N}_0) \rightarrow Val_h \quad // \text{ store}$$

$$State_h = (Vars \rightarrow Val_h) \times Store_h \quad // \text{ states}$$

For simplicity, we set: $0 = \text{Null}$

Let $(\rho, \mu) \in \text{State}_h$. Then we obtain for the new edges:

$$\begin{aligned}
\llbracket x = \text{new}(); \rrbracket (\rho, \mu) &= (\rho \oplus \{x \mapsto \text{ref } h\}, \\
&\quad \mu \oplus \{(\text{ref } h, i) \mapsto 0 \mid i \in \mathbb{N}_0\}) \\
\llbracket x = y[e]; \rrbracket (\rho, \mu) &= (\rho \oplus \{x \mapsto \mu(\rho y, \llbracket e \rrbracket \rho)\}, \mu) \\
\llbracket y[e_1] = e_2; \rrbracket (\rho, \mu) &= (\rho, \mu \oplus \{(\rho y, \llbracket e_1 \rrbracket \rho) \mapsto \llbracket e_2 \rrbracket \rho\})
\end{aligned}$$

Caveat:

This semantics is **too** detailed in that it computes with **absolute** Addresses. Accordingly, the two programs:

$x = \text{new}();$	$y = \text{new}();$
$y = \text{new}();$	$x = \text{new}();$

are **not** considered as equivalent **!!?**

Possible Solution:

Define equivalence only **up to permutation of addresses** **:-)**

Alias Analysis

1. Idea:

- Distinguish **finitely many** classes of blocks.
- Collect all addresses of a block into one set!
- Use sets of addresses as abstract values!

⇒ **Points-to-Analysis**

$Addr^\# = Edges$ // creation edges

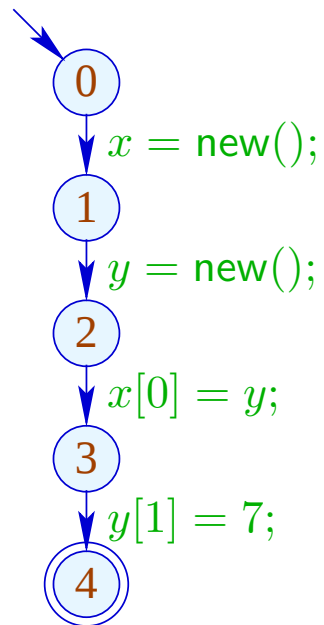
$Val^\# = 2^{Addr^\#}$ // abstract values

$Store^\# = Addr^\# \rightarrow Val^\#$ // abstract store

$State^\# = (Vars \rightarrow Val^\#) \times Store^\#$ // abstract states

// complete lattice !!!

... in the Simple Example:



	x	y	$(0, 1)$
0	$\emptyset$	$\emptyset$	$\emptyset$
1	$\{(0, 1)\}$	$\emptyset$	$\emptyset$
2	$\{(0, 1)\}$	$\{(1, 2)\}$	$\emptyset$
3	$\{(0, 1)\}$	$\{(1, 2)\}$	$\{(1, 2)\}$
4	$\{(0, 1)\}$	$\{(1, 2)\}$	$\{(1, 2)\}$

The Effects of Edges:

$$\llbracket (_, _, _) \rrbracket^\# (D, M) = (D, M)$$

$$\llbracket (_, \text{Pos}(e), _) \rrbracket^\# (D, M) = (D, M)$$

$$\llbracket (_, x = y; _) \rrbracket^\# (D, M) = (D \oplus \{x \mapsto D y\}, M)$$

$$\llbracket (_, x = e; _) \rrbracket^\# (D, M) = (D \oplus \{x \mapsto \emptyset\}, M) \quad , \quad e \notin \text{Vars}$$

$$\llbracket (u, x = \text{new}(); v) \rrbracket^\# (D, M) = (D \oplus \{x \mapsto \{(u, v)\}\}, M)$$

$$\llbracket (_, x = y[e]; _) \rrbracket^\# (D, M) = (D \oplus \{x \mapsto \bigcup \{M(f) \mid f \in D y\}\}, M)$$

$$\llbracket (_, y[e_1] = x; _) \rrbracket^\# (D, M) = (D, M \oplus \{f \mapsto (M f \cup D x) \mid f \in D y\})$$

Caveat:

- The value **Null** has been ignored. Dereferencing of **Null** or negative indices are not detected **:-**(
- **Destructive updates** are only possible for variables, not for blocks in storage!

$\implies$ no information, if not all block entries are initialized before use **:-**((

- The effects now depend on the edge itself.

The analysis cannot be proven correct w.r.t. the reference semantics **:-**(

In order to prove correctness, we first **instrument** the concrete semantics with extra information which records where a block has been created.

...

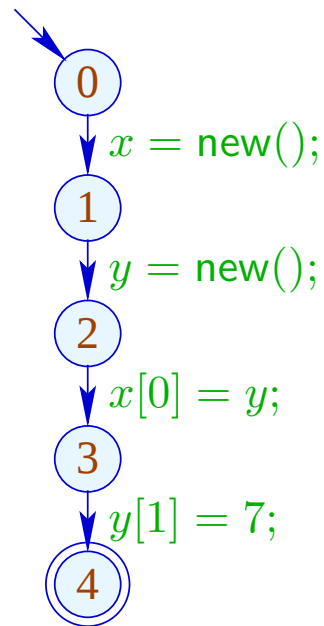
- We compute **possible** points-to information.
- From that, we can extract **may-alias** information.
- The analysis can be rather expensive — without finding very much :-(
:-(
- Separate information for each program point can perhaps be abandoned ??

Alias Analysis

2. Idea:

Compute for each variable and address a value which safely approximates the values at every program point simultaneously !

... in the Simple Example:



x	$\{(0, 1)\}$
y	$\{(1, 2)\}$
$(0, 1)$	$\{(1, 2)\}$
$(1, 2)$	$\emptyset$

Each edge (u, lab, v) gives rise to constraints:

lab	$Constraint$
$x = y;$	$\mathcal{P}[x] \supseteq \mathcal{P}[y]$
$x = \text{new}();$	$\mathcal{P}[x] \supseteq \{(u, v)\}$
$x = y[e];$	$\mathcal{P}[x] \supseteq \bigcup \{\mathcal{P}[f] \mid f \in \mathcal{P}[y]\}$
$y[e_1] = x;$	$\mathcal{P}[f] \supseteq (f \in \mathcal{P}[y]) ? \mathcal{P}[x] : \emptyset$ for all $f \in Addr^\#$

Other edges have no effect :-)

Discussion:

- The resulting constraint system has size $\mathcal{O}(k \cdot n)$ for k abstract addresses and n edges :-(
• The number of necessary iterations is $\mathcal{O}(k + \#Vars)$...
• The computed information is perhaps still too **zu precise !!!**
• In order to prove correctness of a solution $s^\# \in States^\#$ we show:

