Example:  $\{x \mapsto 1, y \mapsto -7\}$   $\Delta$   $\{x \mapsto \top, y \mapsto -7\}$ 

(3) States:

$$\Delta \subseteq ((Vars \to \mathbb{Z}) \times (\mathbb{N} \to \mathbb{Z})) \times (Vars \to \mathbb{Z}^{\top})_{\perp}$$
$$(\rho, \mu) \Delta D \quad \text{iff} \quad \rho \Delta D$$

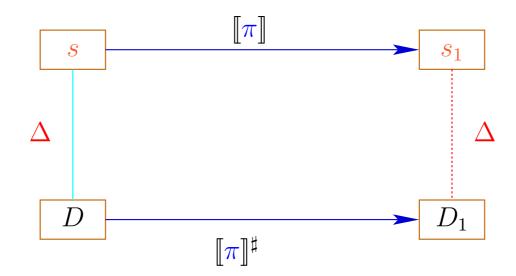
Concretization:

$$\gamma \, D = \left\{ \begin{array}{ll} \emptyset & \text{if} \quad D = \bot \\ \{(\rho, \mu) \mid \forall \, x : \ (\rho \, x) \, \Delta \, (D \, x)\} & \text{otherwise} \end{array} \right.$$

# We show:

(\*) If  $s \Delta D$  and  $[\pi]s$  is defined, then:

$$(\llbracket \pi \rrbracket s) \Delta (\llbracket \pi \rrbracket^{\sharp} D)$$



The abstract semantics simulates the concrete semantics :-)
In particular:

$$\llbracket \pi \rrbracket \, \mathbf{s} \in \gamma \, (\llbracket \pi \rrbracket^{\sharp} \, D)$$

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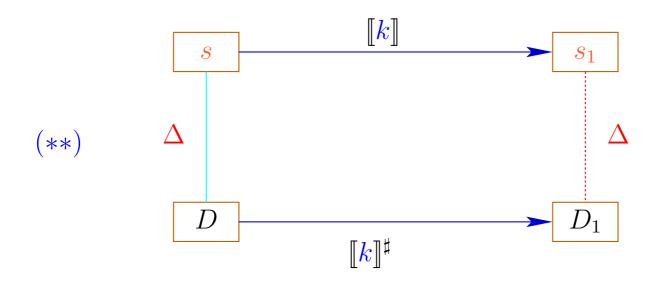
$$\llbracket \pi \rrbracket \, \mathbf{s} \in \gamma \, (\llbracket \pi \rrbracket^{\sharp} \, D)$$

In practice, this means, e.g., that Dx = -7 implies:

$$\rho' x = -7 \text{ for all } \rho' \in \gamma D$$

$$\longrightarrow \rho_1 x = -7 \text{ for } (\rho_1, \underline{\ }) = \llbracket \pi \rrbracket s$$

To prove (\*), we show for every edge k:



Then (\*) follows by induction :-)

To prove (\*\*), we show for every expression e: (\*\*\*)  $(\llbracket e \rrbracket \rho)$   $\Delta$   $(\llbracket e \rrbracket^{\sharp} D)$  whenever  $\rho \Delta D$ 

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To prove (\*\*\*), we show for every operator  $\square$ :

 $(x \Box y) \Delta (x^{\sharp} \Box^{\sharp} y^{\sharp})$  whenever  $x \Delta x^{\sharp} \wedge y \Delta y^{\sharp}$ 

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 whenever  $x \ \Delta \ x^{\sharp} \wedge y \ \Delta \ y^{\sharp}$ 

This precisely was how we have defined the operators  $\Box^{\sharp}$ :-)

Now, (\*\*) is proved by case distinction on the edge labels lab.

Let  $s = (\rho, \mu) \ \Delta \ D$ . In particular,  $\bot \neq D$ :  $Vars \to \mathbb{Z}^{\top}$ 

Case 
$$x = e$$
;:

$$\rho_1 = \rho \oplus \{x \mapsto \llbracket e \rrbracket \rho\} \quad \mu_1 = \mu$$

$$D_1 = D \oplus \{x \mapsto \llbracket e \rrbracket^{\sharp} D\}$$

$$\longrightarrow$$
  $(\rho_1, \mu_1) \Delta D_1$ 

Case 
$$x = M[e];$$
:
$$\rho_1 = \rho \oplus \{x \mapsto \mu(\llbracket e \rrbracket^{\sharp} \rho)\} \qquad \mu_1 = \mu$$

$$D_1 = D \oplus \{x \mapsto \top\}$$

$$\Longrightarrow (\rho_1, \mu_1) \Delta D_1$$

Case 
$$M[e_1] = e_2;$$
:
$$\rho_1 = \rho \qquad \mu_1 = \mu \oplus \{ [e_1]^{\sharp} \rho \mapsto [e_2]^{\sharp} \rho \}$$

$$D_1 = D$$

$$\longrightarrow (\rho_1, \mu_1) \Delta D_1$$

Case 
$$Neg(e)$$
:  $(\rho_1, \mu_1) = s$  where: 
$$0 = [e] \rho$$

$$\Delta \quad [e]^{\sharp} D$$

$$\longrightarrow \quad 0 \quad \sqsubseteq \quad [e]^{\sharp} D$$

$$\longrightarrow \quad \bot \quad \neq \quad D_1 = D$$

$$\longrightarrow \quad (\rho_1, \mu_1) \quad \Delta \quad D_1$$

Case 
$$Pos(e)$$
:  $(\rho_1, \mu_1) = s$  where:

$$0 \neq [e] \rho$$

$$\Delta [e]^{\sharp} D$$

$$\Longrightarrow 0 \neq [e]^{\sharp} D$$

$$\Longrightarrow \bot \neq D_{1} = D$$

$$\Longrightarrow (\rho_{1}, \mu_{1}) \Delta D_{1}$$

:-)

We conclude: The assertion (\*) is true :-))

The MOP-Solution:

$$\mathcal{D}^*[v] = \bigsqcup\{\llbracket\pi\rrbracket^\sharp \ D_\top \mid \pi : start \to^* v\}$$

where  $D_{\top} x = \top$   $(x \in Vars)$ .

We conclude: The assertion (\*) is true :-))

The MOP-Solution:

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where  $D_{\top} x = \top$   $(x \in Vars)$ .

By (\*), we have for all initial states s and all program executions  $\pi$  which reach v:

$$(\llbracket \pi \rrbracket s) \Delta (\mathcal{D}^*[v])$$

We conclude: The assertion (\*) is true :-))

The MOP-Solution

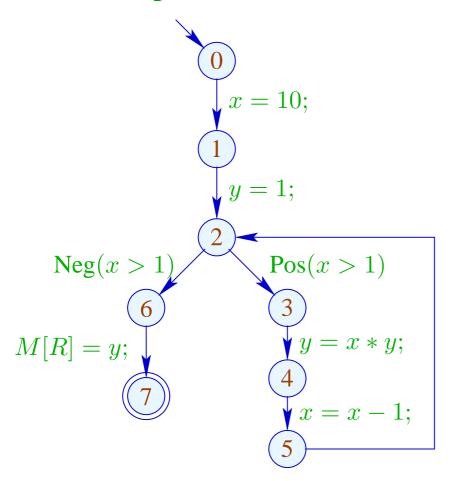
$$\mathcal{D}^*[v] = \bigsqcup \{ \llbracket \pi \rrbracket^{\sharp} \ D_{\top} \mid \pi : start \to^* v \}$$

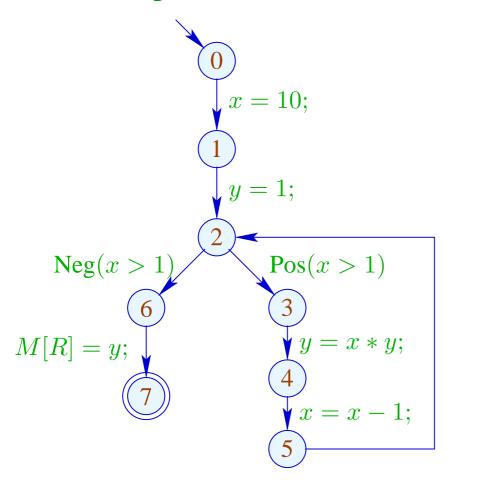
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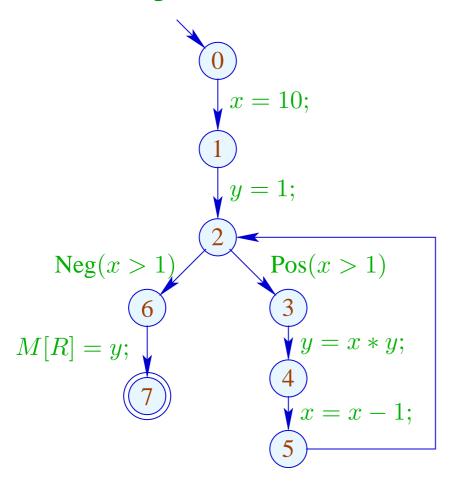
$$(\llbracket \pi \rrbracket s) \Delta (\mathcal{D}^*[v])$$

In order to approximate the MOP, we use our constraint system :-))

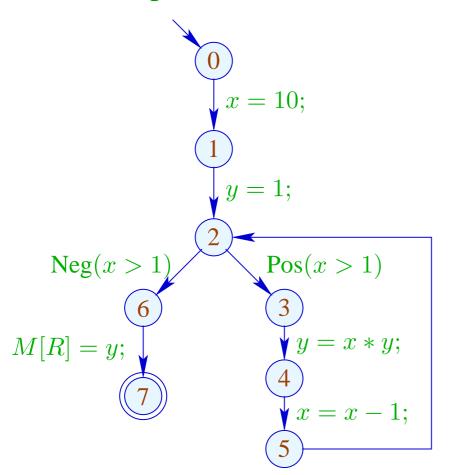




		1		
	1			
	x	y		
0	T	T		
1	10	T		
2	10	1		
3	10	1		
4	10   10			
5	9   10			
6				
7				



	1		2	
	x	y	x	y
0	Т	T	T	T
1	10	Т	10	$\top$
2	10	1	$\mid \top \mid$	$\top$
3	10	1	$\mid \top \mid$	$\top$
4	10	10	$\mid \top \mid$	$\top$
5	9	10	$\mid \top \mid$	$\top$
6		L		$\mid \top \mid$
7		L		$\top$



	1		2		3	
	x	y	x	y	x	y
0	T	Т	Т	T		
1	10	Т	10	$  \top  $		
2	10	1	T	$  \top  $		
3	10	1	T	$  \top  $		
4	10	10	T	$  \top  $	di	to
5	9	10	T	$  \top  $		
6			T	$\mid \top \mid$		
7	上		T	$\mid \top \mid$		

#### Conclusion:

Although we compute with concrete values, we fail to compute everything :-(

The fixpoint iteration, at least, is guaranteed to terminate:

For n program points and m variables, we maximally need:  $n \cdot (m+1)$  rounds :-)

#### Caveat:

The effects of edge are not distributive!!!

Counter Example: 
$$f = [x = x + y]^{\sharp}$$

Let 
$$D_1 = \{x \mapsto 2, y \mapsto 3\}$$
  
 $D_2 = \{x \mapsto 3, y \mapsto 2\}$   
Dann  $f D_1 \sqcup f D_2 = \{x \mapsto 5, y \mapsto 3\} \sqcup \{x \mapsto 5, y \mapsto 2\}$   
 $= \{x \mapsto 5, y \mapsto \top\}$   
 $\neq \{x \mapsto \top, y \mapsto \top\}$   
 $= f\{x \mapsto \top, y \mapsto \top\}$   
 $= f(D_1 \sqcup D_2)$   
:-((

### We conclude:

The least solution  $\mathcal{D}$  of the constraint system in general yields only an upper approximation of the MOP, i.e.,

$$\mathcal{D}^*[v] \subseteq \mathcal{D}[v]$$

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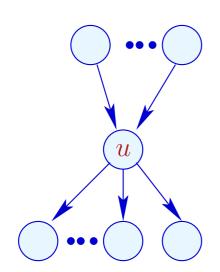
As an upper approximation,  $\mathcal{D}[v]$  nonetheless describes the result of every program execution  $\pi$  which reaches v:

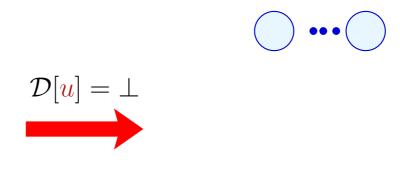
$$(\llbracket \pi \rrbracket (\rho, \mu)) \Delta (\mathcal{D}[v])$$

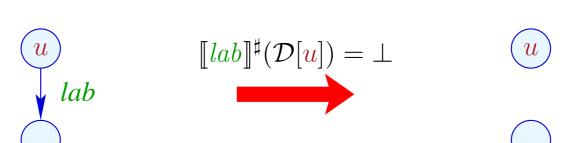
whenever  $\llbracket \pi \rrbracket (\rho, \mu)$  is defined ;-))

### Transformation 4:

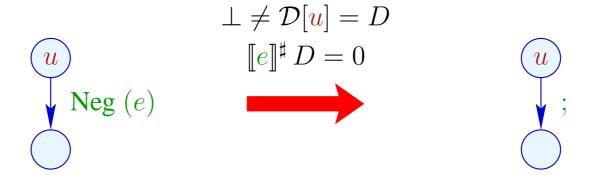
#### Removal of Dead Code

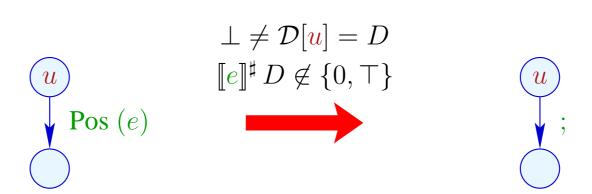




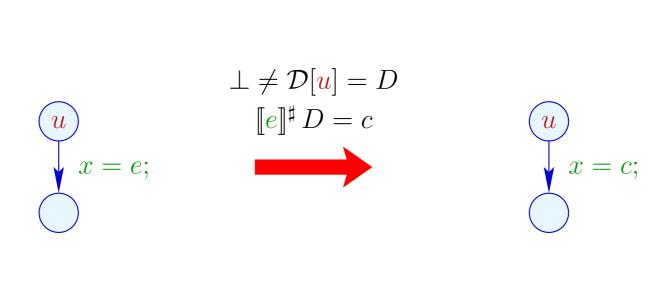


### Transformation 4 (cont.): Removal of Dead Code





## Transformation 4 (cont.): Simplified Expressions



### **Extensions:**

• Instead of complete right-hand sides, also subexpressions could be simplified:

$$x + (3*y) \xrightarrow{\{x \mapsto \top, y \mapsto 5\}} x + 15$$

... and further simplifications be applied, e.g.:

$$\begin{array}{ccc}
x * 0 & \Longrightarrow & 0 \\
x * 1 & \Longrightarrow & x \\
x + 0 & \Longrightarrow & x \\
x - 0 & \Longrightarrow & x
\end{array}$$

• So far, the information of conditions has not yet be optimally exploited:

if 
$$(x == 7)$$
  
$$y = x + 3;$$

Even if the value of x before the if statement is unknown, we at least know that x definitely has the value 7 — whenever the then-part is entered :-)

Therefore, we can define:

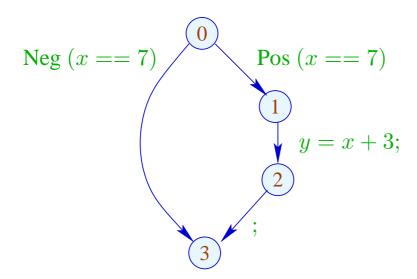
$$[Pos (x == e)]^{\sharp} D = \begin{cases} D & \text{if } [x == e]^{\sharp} D = 1 \\ \bot & \text{if } [x == e]^{\sharp} D = 0 \\ D_1 & \text{otherwise} \end{cases}$$

where

$$D_1 = D \oplus \{x \mapsto (D \, x \sqcap \llbracket e \rrbracket^{\sharp} \, D)\}$$

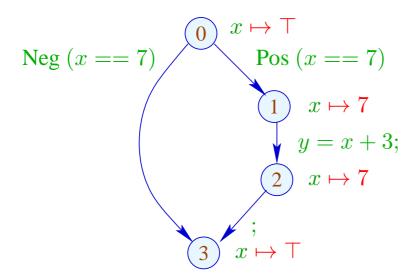
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